

Model-reduced 4D-Var data assimilation in the phytoplankton bloom prediction

Joanna S. Pelc^{1,2}, Ghada El Serafy², Arnold W. Heemink¹

Special thanks to Hans Los and Jan van Beek

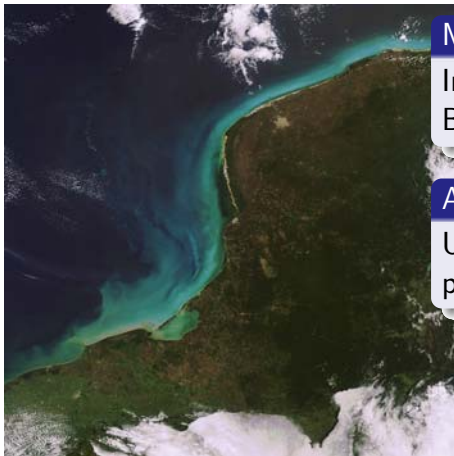
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Outline

- 1 Introduction
- 2 BLOOM/GEM (Generic Ecological Model)
- 3 POD Model Reduced 4D-Var
- 4 Results
- 5 Summary

Introduction



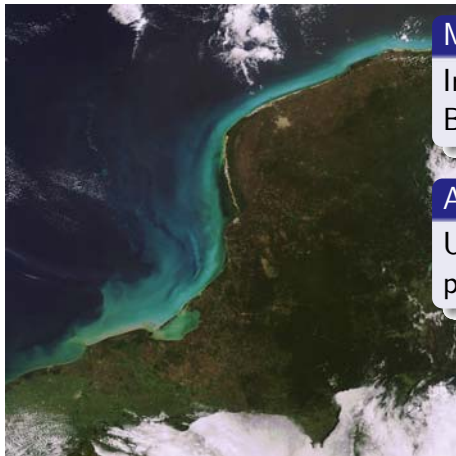
Main objective

Improve the predictions of the BLOOM/GEM model

Approach

Update the uncertain parameters of the model

Introduction



Main objective

Improve the predictions of the BLOOM/GEM model

Approach

Update the uncertain parameters of the model

Which parameters are uncertain?

Introduction

What has been already done

~250
parameters

→ Out of approximately 250 parameters of the model, **EXPERTS** have selected a group of 71 the most significant

~70
parameters

→ Out of 71 parameters, 20 the most significant were selected by means of **SENSITIVITY ANALYSIS**

What is to be done

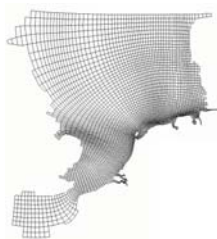
~20
parameters

→ Approximately 20 parameters is going to be updated to improve the model output, by means of **DATA ASSIMILATION**

Model: BLOOM/GEM (Generic Ecological Model)

State vector: $x_i \in \mathbb{R}^{25 \cdot 4350}$, where i stands for time
 $x_i = [Alg, Nut (NH_4, NO_3, PO_4, Si), Det, DetSed, Oxy]_i^T$

Parameter vector: $\alpha \in \mathbb{R}^{71}$
 $\alpha = [ExtVL, NCR, PCR, SCR, ChlaCR, PPM_{max}]^T$



Forward model

$$x_i = \mathcal{M}_i(x_{i-1}, \alpha)$$

\mathcal{M}_i integrates the state x_{i-1} from time t_i to time t_{i-1}

Observation operator

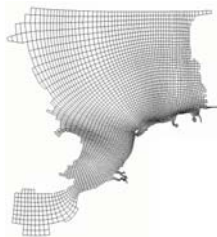
$$y_i = \mathcal{H}_i(x_i, \alpha)$$

\mathcal{H}_i translates model state x_i into a value in observation space

Model: BLOOM/GEM (Generic Ecological Model)

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$$\sum_{j=1}^{12} \text{ChlaCR}_j \cdot \text{Alg}_j$$

4D-Var: 4D Variational Data Assimilation

Cost function in 4D-Var

$$J(\alpha) = \sum_{i=1}^n \underbrace{(\mathcal{H}_i(x_i) - y_i)^T}_{\text{Distances}} R_i^{-1} \underbrace{(\mathcal{H}_i(x_i) - y_i)}_{\text{Distances}} + \underbrace{(\alpha - \alpha_b)^T B^{-1} (\alpha - \alpha_b)}_{\text{Background term}}$$

minimization with
constraints:

$$x_i = \mathcal{M}_i(x_{i-1}, \alpha)$$

B background error covariance matrix
 R_i observation error covariance matrix

**To minimize J
over α , we need:**
 $\nabla_{\alpha} J(\alpha)$

Needed to get $\nabla_{\alpha} J(\alpha)$

- exact derivatives of the model
- approximate the derivatives of the model with finite differences

4D-Var: 4D Variational Data Assimilation

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Needed to get $\nabla_{\alpha} J(\alpha)$

- **Very complicated!**
- approximate the derivatives of the model with finite differences

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Needed to get $\nabla_{\alpha} J(\alpha)$

- **Very complicated!**
- **Very time consuming!**

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over α , we need:**
 $\nabla_{\alpha} J(\alpha)$

Solution

POD Model-reduced 4D-Var

(Vermeulen and Heemink, MWR, 2006)

POD Model Reduced 4D-Var

Incremental cost function in 4D-Var

$$J(\delta\alpha) = \sum_{i=1}^n (\mathbf{H}_i(\delta\mathbf{x}_i, \delta\alpha) + \mathbf{d}_i)^T R_i^{-1} (\mathbf{H}_i(\delta\mathbf{x}_i, \delta\alpha) + \mathbf{d}_i) + \delta\alpha^T B^{-1} \delta\alpha$$

minimization with constraints

$$\delta\mathbf{x}_i = \frac{\partial \mathcal{M}_i(\mathbf{x}_{i-1}^b, \alpha^b)}{\partial \mathbf{x}_{i-1}} \delta\mathbf{x}_{i-1} + \frac{\partial \mathcal{M}_i(\mathbf{x}_{i-1}^b, \alpha^b)}{\partial \alpha} \delta\alpha$$

POD Model Reduced 4D-Var

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**With a small number of parameters, the
finite differences method is feasible**

POD Model Reduced 4D-Var

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minimization with constraints

$$\delta x_i = \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial x_{i-1}} \delta x_{i-1} + \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial \alpha} \delta \alpha$$

If the size of the state x is huge, the finite differences would be too expensive

POD Model Reduced 4D-Var

Incremental equation

$$\delta x_i = \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial x_{i-1}} \delta x_{i-1} + \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial \alpha} \delta \alpha$$

Project the increments into smaller subspace

$$P^T \delta x_i = P^T \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial x_{i-1}} \delta x_{i-1} + P^T \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial \alpha} \delta \alpha$$

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$$P^T \delta x_i = P^T \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial x_{i-1}} P P^T \delta x_{i-1} + P^T \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial \alpha} \delta \alpha$$

POD Model Reduced 4D-Var

Incremental equation

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$$\underbrace{P^T \delta x_i}_{\delta z_i} = P^T \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial x_{i-1}} P \underbrace{P^T \delta x_{i-1}}_{\delta z_{i-1}} + P^T \frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial \alpha} \delta \alpha$$

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$\delta z_i = P^T \delta x_i$ increment of the state in the reduced space

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$\delta z_i = P^T \delta x_i$ increment of the state in the reduced space

$$\frac{\partial \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\partial x_{i-1}} p \simeq \frac{\mathcal{M}_i(x_{i-1}^b + \epsilon p, \alpha^b) - \mathcal{M}_i(x_{i-1}^b, \alpha^b)}{\epsilon}$$

**directional derivative
 approximation**

How to get matrix P ?

How to project into a smaller subspace, such that the most important dynamics of the system are kept?

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How to project into a smaller subspace, such that the most important dynamics of the system are kept?

STEP 1: Generate ensemble of perturbed model simulations

$$\begin{aligned}\alpha^b + \Delta\alpha_1 &\rightarrow x_1^{\Delta 1}, x_2^{\Delta 1}, \dots, x_n^{\Delta 1} \\ \alpha^b + \Delta\alpha_2 &\rightarrow x_1^{\Delta 2}, x_2^{\Delta 2}, \dots, x_n^{\Delta 2}\end{aligned}$$

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STEP 2: Create a covariance matrix

$$\mathbf{C}_X = \mathbf{\Delta X} \mathbf{\Delta X}^T / (n - 1)$$

How to get matrix \mathbf{P} ?

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STEP 2: Create a covariance matrix

$$\mathbf{C}_X = \Delta\mathbf{X} \Delta\mathbf{X}^T / (n - 1)$$

STEP 3: Decompose \mathbf{C}_X with eigenvalue decomposition

$$\Delta\mathbf{X} \Delta\mathbf{X}^T / (n - 1) = \mathbf{P} \mathbf{D} \mathbf{P}^T$$

\mathbf{P} - eigenvectors, \mathbf{D} - diagonal matrix with eigenvalues

How to get matrix P?

Covariance matrix of ΔX :

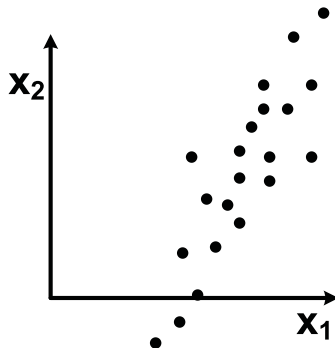
$$\Delta X \Delta X^T / (n - 1) = P D P^T$$

$$P^T \Delta X (P^T \Delta X)^T / (n - 1) = D$$

$$\Delta Z \Delta Z^T / (n - 1) = D$$

Covariance matrix of ΔZ :

$$C_Z = D$$



How to get matrix P?

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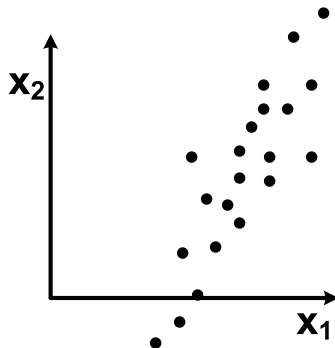
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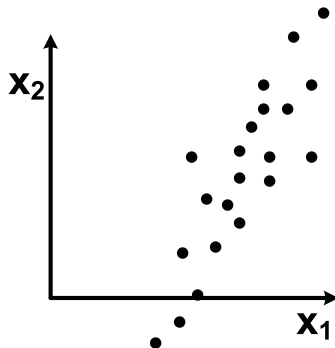
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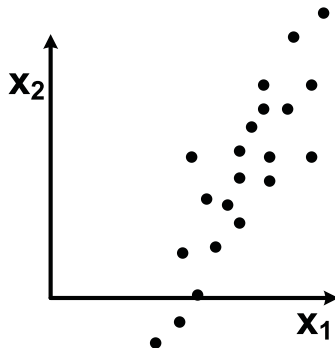
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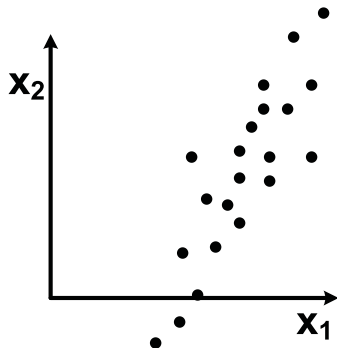
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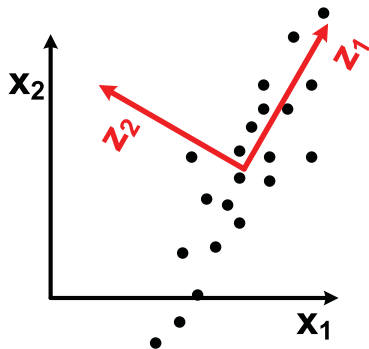
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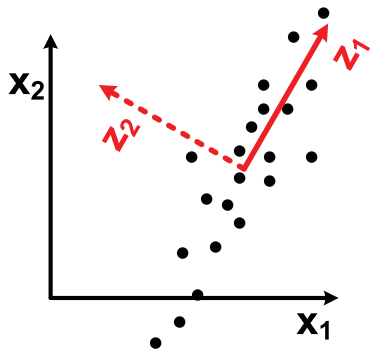
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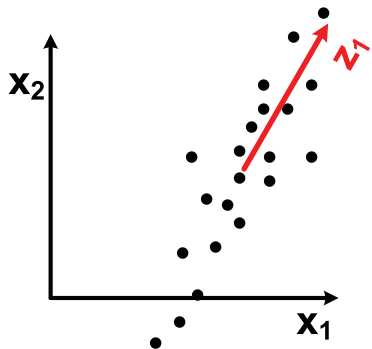
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How to get matrix \mathbf{P} ?

Covariance matrix of $\Delta\mathbf{X}$:

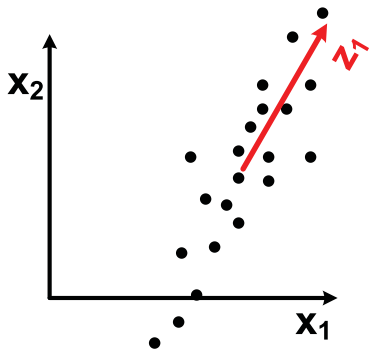
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$$\Delta\mathbf{Z} \Delta\mathbf{Z}^T / (n - 1) = \mathbf{D}$$

Covariance matrix of $\Delta\mathbf{Z}$:

$$\mathbf{C}_Z = \mathbf{D}$$



The matrix \mathbf{P}

Selection of the eigenvectors corresponding to the highest eigenvalues will create the projection matrix \mathbf{P}

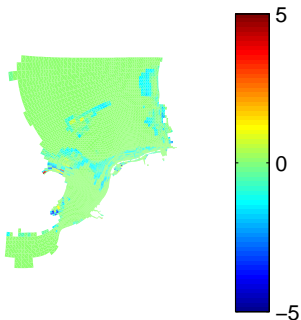
Results POD-Reduced Model

Experiment set up

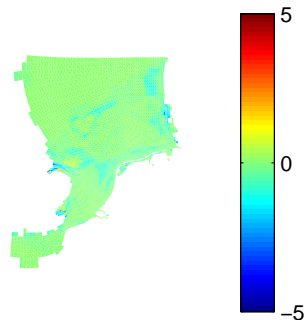
parameter:	ExtVLIM Extinction of visible light due to inorganic matter
parameter background	0.025
parameter perturbed	0.015, 0.035
results shown for	0.03
starting time:	26-Feb-2003
time of simulation:	14 days
time step:	1 day
number of snapshots:	26
energy recovered	90 %

Results POD-Reduced Model

subs 4(1), 28-Feb-2003
Chlfa : Chlorophyll-a concentration
Truth



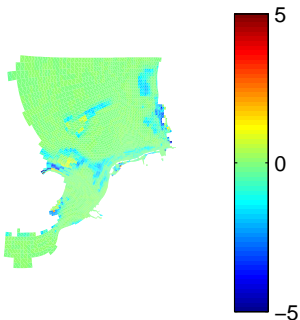
subs 4(1), 28-Feb-2003
Chlfa : Chlorophyll-a concentration
RedMod



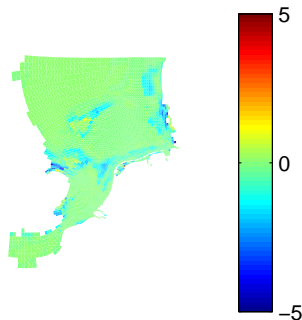
Increment of the reduced model compared with the **increment** of the true model, comparison for the Chlorophyll-a concentration

Results POD-Reduced Model

subs 4(1), 2-Mar-2003
Chlfa : Chlorophyll-a concentration
Truth



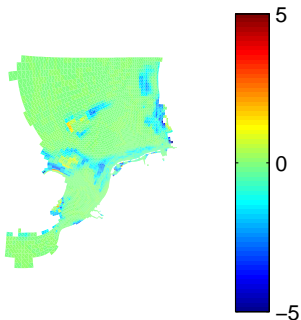
subs 4(1), 2-Mar-2003
Chlfa : Chlorophyll-a concentration
RedMod



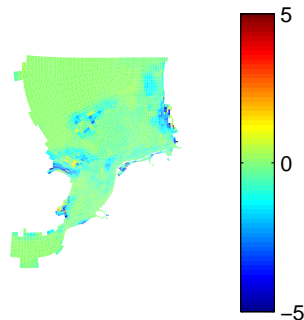
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Results Reduced Model

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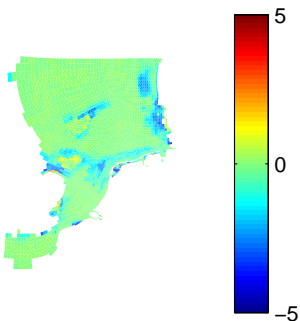
subs 4(1), 4-Mar-2003
Chlfa : Chlorophyll-a concentration
RedMod



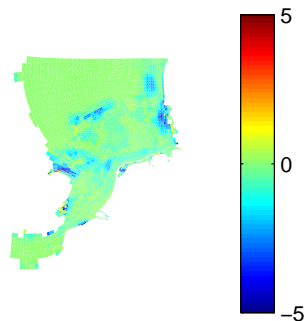
Increment of the reduced model compared with the **increment** of the true model, comparison for the Chlorophyll-a concentration

Results Reduced Model

subs 4(1), 6-Mar-2003
Chlfa : Chlorophyll-a concentration
Truth



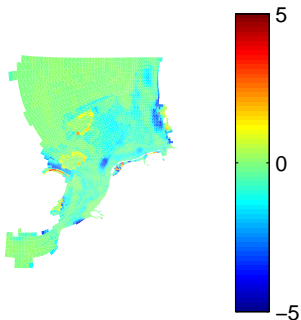
subs 4(1), 6-Mar-2003
Chlfa : Chlorophyll-a concentration
RedMod



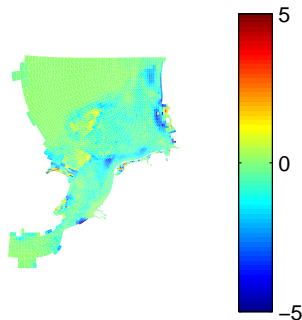
Increment of the reduced model compared with the **increment** of the true model, comparison for the Chlorophyll-a concentration

Results Reduced Model

subs 4(1), 8-Mar-2003
Chlfa : Chlorophyll-a concentration
Truth



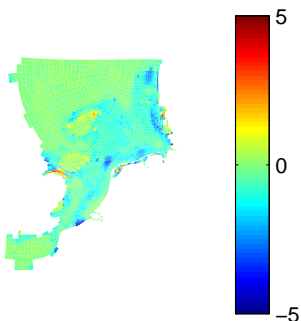
subs 4(1), 8-Mar-2003
Chlfa : Chlorophyll-a concentration
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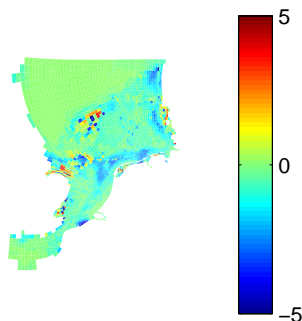
Increment of the reduced model compared with the **increment** of the true model, comparison for the Chlorophyll-a concentration

Results Reduced Model

subs 4(1), 10-Mar-2003
Chlfa : Chlorophyll-a concentration
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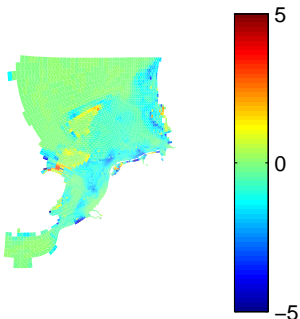
subs 4(1), 10-Mar-2003
Chlfa : Chlorophyll-a concentration
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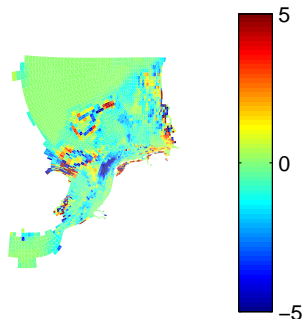
Increment of the reduced model compared with the **increment** of the true model, comparison for the Chlorophyll-a concentration

Results Reduced Model

subs 4(1), 12-Mar-2003
Chlfa : Chlorophyll-a concentration
Truth

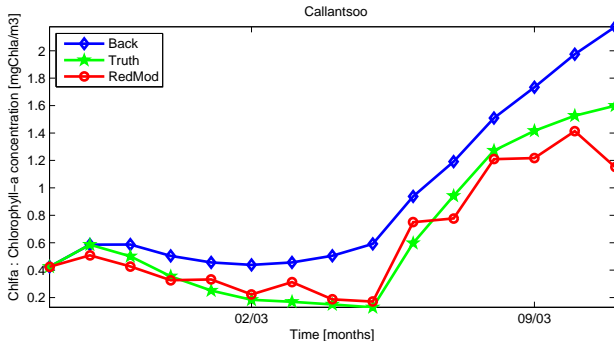


subs 4(1), 12-Mar-2003
Chlfa : Chlorophyll-a concentration
RedMod



Increment of the reduced model compared with the **increment** of the true model, comparison for the Chlorophyll-a concentration

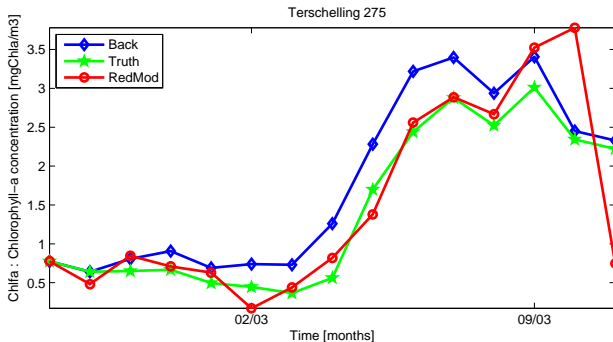
Results Reduced Model - stations



Chlorophyll-a concentration within time at station Callantsoo.

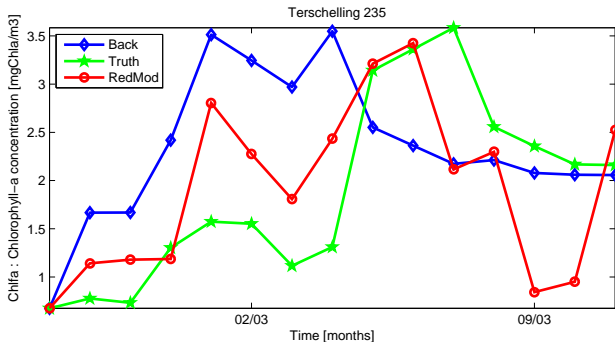
Comparison between background run of the model, reduced model for a chosen parameter and true model for same parameter.

Results Reduced Model - stations



Chlorophyll-a concentration within time at station Terschelling 275km. Comparison between background run of the model, reduced model for a chosen parameter and true model for same parameter.

Results Reduced Model - stations



Chlorophyll-a concentration within time at station Terschelling 235km. Comparison between background run of the model, reduced model for a chosen parameter and true model for same parameter.

Summary

- POD-Reduced Forward model:
 - captures very well the behavior of the original model
- POD-Reduced Adjoint model approximation:
 - reasonably accurate
 - feasible in time
 - does not need exact derivatives

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Future work

- 4D Variational Assimilation using the POD-Reduced model approximations (POD-Model Reduced 4D-Var)
 - Twin experiment
 - Real data case (satellite and in-situ measurements)

Thank you for your attention!

Questions?

