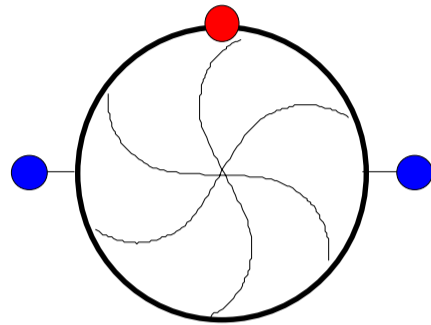


1 Turbine

1.1 Turbine (class)



Turbine with adjustable vanes

Fall type

type label	description	active
Turbine	A turbine whose speed is controlled by its vane position, absorbed power and upstream/downstream hydraulic conditions.	yes

The turbine is an active Fall-type component. It is controlled by its vane position, the power absorbed by the electricity grid and the upstream/downstream hydraulic conditions.

Notes:

1. The absorbed power must be less than the maximum available hydraulic power ($= \rho gQH\eta$) at all times.
2. A hydraulic system based on BoundH boundary conditions are recommended. Convergence problems could be encountered when a BoundQ boundary condition is used (multiple solutions could exist).

1.1.1 Mathematical model

The basic equations governing the flow in the turbine are:

Continuity

$$Q_1 = Q_2 \quad (1.1)$$

Head balance

$$H_1 - H_2 = H(Q, N, Y) \quad (1.2)$$

Torque-speed

$$T(Q, N, Y)N - P_{abs} = I_p N \frac{dN}{dt} \quad (1.3)$$

Where

Symbol	Description	SI-units
Q_1	upstream discharge	[m ³ /s]
Q_2	downstream discharge	[m ³ /s]
H_1	upstream head	[m]
H_2	downstream head	[m]
$H(Q, N, Y)$	Head loss across the turbine	[m]
$T(Q, N, Y)$	Torque generated by the turbine	[Nm]
N	Turbine speed	[rad/s]
Y	Turbine vane position	[rad]
TN	Power generated by the turbine	[W]
P_{abs}	Power absorbed by the power grid	[W]
I_p	Turbine polar moment of inertia	[kg.m ²]
t	time	[s]

1.1.2 Turbine data curves

In order to solve equations 1.1, 1.2 and 1.3 the turbine headloss $H(Q, N, Y)$ and torque $T(Q, N, Y)$ need to be determined. These values are calculated from the data provided by the manufacturer, using the following relationships:

$$Q(H, N, Y) = Q_{11}(N_{11}) D^2 \sqrt{H} \quad (1.4)$$

$$T(H, N, Y) = T_{11}(N_{11}) D^3 H \quad (1.5)$$

with

$$N_{11} = \frac{ND}{\sqrt{H}} \quad (1.6)$$

Where $Q_{11}(N_{11})$ and $T_{11}(N_{11})$ are the unit value curves provided by the turbine

manufacturer. D is the reference diameter. Usually the $Q_{11}(N_{11})$ and $T_{11}(N_{11})$ unit value curves do not allow for accurate interpolation of an arbitrary vane position. Improved interpolation is achieved by transforming the unit value curves into $Q_{11}(N_{11} y/y_{\max})$ and $T_{11}(N_{11} y/y_{\max})$ curves. The Wanda turbine component computes these transformed unit value curves from two .trb input files, which contain a set of interpolation curves.

Figure 1.1 presents an example set of transformed unit value curves. For a fixed head drop, vane position, diameter and speed, the discharge and torque can be found. For example:

speed: $N = 600$ rpm
 reference diameter: $D = 1590$ mm
 head drop: $H = 350$ m
 vane position: $y/y_{\max} = 1$ (100%)

$$N_{11} = \frac{ND}{\sqrt{H}} = 51 \text{ rpm} \cdot \text{m}^{1/2}$$

from Figure 1.1: $Q_{11} = 0.224 \text{ m}^{1/2} / \text{s}$ and $T_{11} = 370 \text{ N} / \text{m}^3$

and with equations (1.4) and (1.5): $Q = 10.6 \text{ m}^3 / \text{s}$ and $T = 521 \text{ kNm}$

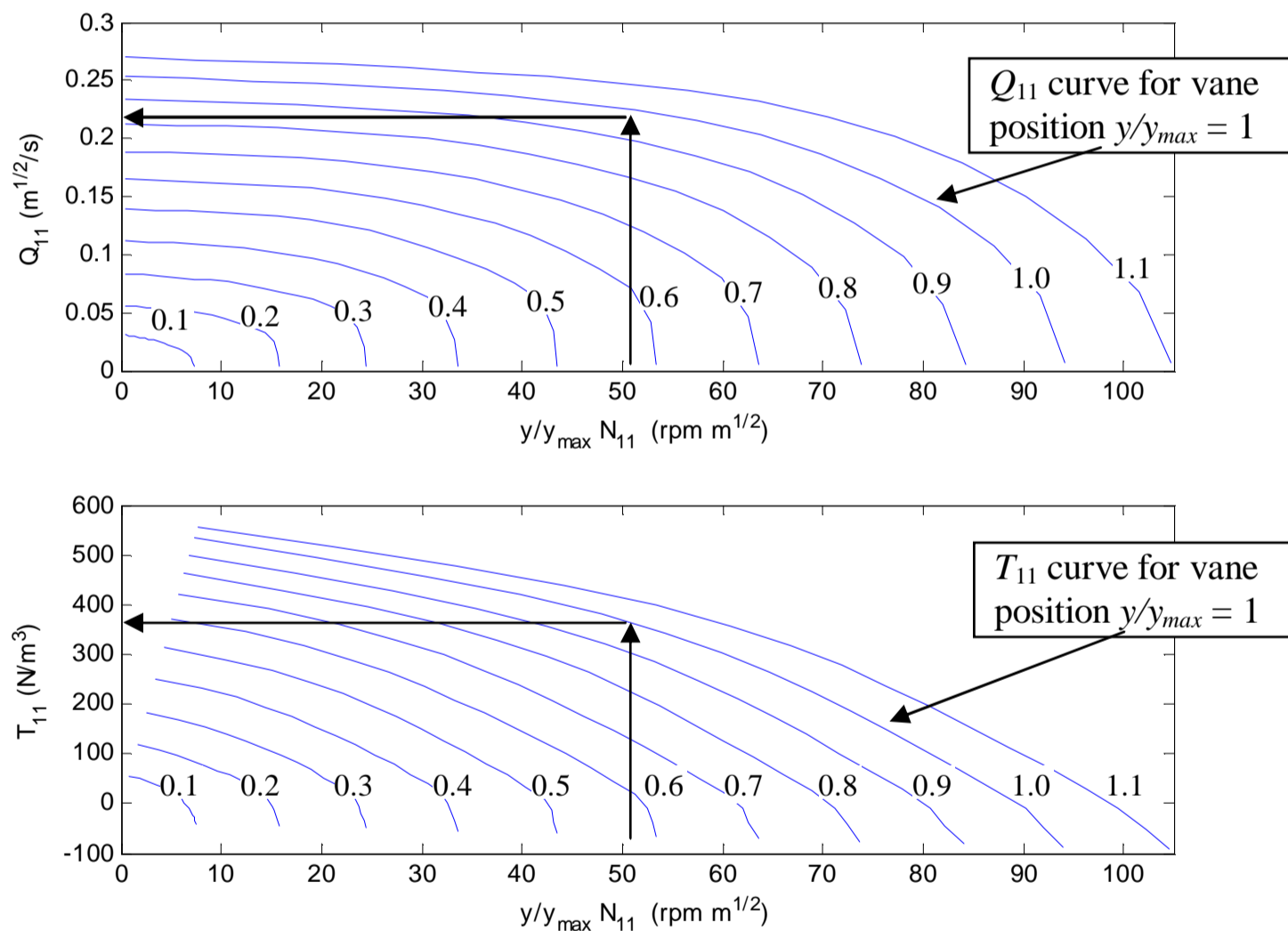


Figure 1.1: Example turbine unit value curves

References

- [1] E.B. Wylie, V.L. Streeter, "Fluid Transients", McGraw-Hill, New York, 1978.
- [2] A.P. Boldy, N. Walmsley "Representation of the characteristics of reversible pump turbines for use in waterhammer simulations", Paper G1, Fourth Int. conference on Pressure Surges, University of Bath, England, September 21-23, 1983
- [3] C.S. Martin, "Transformation of pump-turbine characteristics for hydraulic transient analysis", Proceedings, Eleventh Symposium of the section on Hydraulic Machinery, Equipment and Cavitation, IAHR, Amsterdam, 1982, Paper 30

1.2 Turbine model

1.2.1 Hydraulic specifications

Description	Input	SI-unit	Default	Remarks
Turbine file nr	Real	-	1	Reference number for the turbine input data (.trb) files: CASE_###T11.trb and CASE_###Q11.trb. See below.
Reference diameter	Real	[m]		Turbine diameter related to the unit value curves in the input files.
Polar moment of inertia	Real	[kg.m ²]		Moment of inertia.
Max open vane position	Real	[rad]		Vane position (angle) when completely open.
Initial vane position	Real	[rad]		Vane position at t=0 s.
Initial Power absorbed	Real	[W]		Power absorbed by the electricity grid at t=0 s.
Initial speed	Real	[rad/s]		Speed at t=0. A realistic value should be used (see below).
Action table	Real	[W]		The absorbed power can be changed using this time-power action table.

NOTE: Turbine file format

The 'interpolation curves' in the turbine data files can be used to determine the values of $Q_{11}(N_{11} y/y_{\max})$ and $T_{11}(N_{11} y/y_{\max})$ or to reconstruct the unit value curves for an arbitrary vane position. The data files contain the number of vane positions and an array of vane positions in the header and the number of interpolation curves and the actual interpolation curves (x and y values) in the body. Rows starting with '*' are ignored.

The file name consists of the CASENAME, the number specified in the input field, Q_{11} or T_{11} and the .trb extension. The interpolation curves are sorted from lower $N_{11} y/y_{\max}$ values at the top of the file to higher values at the bottom.

The interpolation curves define the points for each vane position. Therefore, the number of columns for each curve is the same as the number of vane positions. Each curve has a row for $N_{11} y/y_{\max}$ [rpm.m^{1/2}] and a row for Q_{11} [m^{1/2}/s] or T_{11} [N/m³] corresponding to the actual vane positions. Please note that the units of N_{11} in the turbine files are defined as [rpm.m^{1/2}], which is not conform the SI-unit standard.

```

1 * Francis turbine (T11 versus N11*y/ymax)
2 *
3 *
4 * The first row gives the vane positions: Number of vane positions = number of columns.
5 *   In this file we have 11 vane positions hence we have 11 columns.
6 * # VANE POSITIONS
7 11
8 * List of vane positions (y/ymax fractions)
9 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0 1.1
10 *
11 *
12 * # INTERPOLATION CURVES
13 17
14 * Each interpolation curve has two rows; the columns correspond to the vane positions above
15 * row 1: N11*y/ymax values
16 * row 2: T11 values
17 *
18 * Interpolation curve 1:
19 8.1382344E-01 1.6410418E+00 2.5290259E+00 3.4465626E+00 4.2869270E+00 5.0758145E+00 5.7422397E+00
20 5.6154618E+01 1.1724455E+02 1.8282203E+02 2.5058196E+02 3.1264273E+02 3.7090193E+02 4.2011732E+02
21 * Interpolation curve 2
22 1.8086890E+00 3.8293637E+00 5.7864977E+00 7.9790587E+00 1.0351830E+01 1.2483895E+01 1.4767228E+01
23 5.0161878E+01 1.0728041E+02 1.6857407E+02 2.3185225E+02 2.8992266E+02 3.4446175E+02 3.9048861E+02
24 * Interpolation curve 3
25 2.7514762E+00 5.4989515E+00 8.3473620E+00 1.1498953E+01 1.5104397E+01 1.8180247E+01 2.1755054E+01
26 4.4160669E+01 9.7212141E+01 1.5418070E+02 2.1289943E+02 2.6688356E+02 3.1759231E+02 3.6030446E+02
27 * Interpolation curve 4
28 3.5531236E+00 6.9232355E+00 1.0485109E+01 1.4426752E+01 1.8905556E+01 2.2808252E+01 2.7477029E+01

```

Figure 1.2: Example of a part of the input file “Turbine_001T11.trb”

NOTE: Initial speed

An estimate of the initial speed should be given such the generated and absorbed power are in equilibrium at $t=0$ s. The equilibrium initial speed can be found through trial-and-error calculation where hydraulic conditions, vane position and absorbed power are kept constant during the simulation. By plotting the turbine speed in time series, the equilibrium speed can be identified. However, multiple solutions exist. The user has to check whether the Generated Power equals the Absorbed Power. The right equilibrium speed must result in the turbine generated power being equal to the absorbed power at $t=0$.

1.2.2 Component specific output

Description	SI-unit	Remarks
Turbine speed	[rad/s]	Rotational speed of the turbine
Vane position	[rad]	Position (angle) of the vanes
Generated power	[W]	Power generated by the turbine
Absorbed power	[W]	Power absorbed by generator / electricity grid
Torque generated	[Nm]	Torque generated by the turbine
Torque absorbed	[Nm]	Torque absorbed by the generator
N11	[rpm.m ^{1/2}]	Transformed turbine speed (in rpm in stead of rad/s)
Q11	[m ^{1/2} /s]	Transformed turbine discharge
T11	[N/m ³]	Transformed turbine torque

1.2.3 H-actions

The turbine component differs from other components regarding H-actions. Although for most components the H-action controlled by the control signal line is the same as what can be controlled through an action table, the turbine has two different H-actions:

- Action table: changes the absorbed power
- Control signal line: changes the vane position

1.2.4 Component messages

Message

Warning: Could not solve Torque-speed equation: Inappropriate Q11/T11 turbine data, too large absorbed power or too small polar moment?

Warning: Could not solve head for given discharge and speed.

Warning: N11*y/ymax below turbine data range

Warning: N11*y/ymax above turbine data range

Error: Input file not found

Error: Input file already in use by other RDFILE

Error: Error with input file

Error: Error in turbine file

Error: decrease NVANES

Error: decrease NCURVES

Error: Inconsistent initial vane position at t=0s and input of control system

Error: Control system gives negative vane position

Explanation

A solution could not be found for the torque-speed equation at the start of the time-step. This might be caused by a too small polar moment, incorrect Q11/T11 turbine data or that the absorbed power is larger than $\rho gQH\eta$.

Unable to compute a head from the Q11/T11 turbine files (.trb), based on the present discharge and speed.

Computed N11*y/ymax value is less than the minimum value in the Q11/T11 turbine files (.trb)

Computed N11*y/ymax value is larger than the maximum value in the Q11/T11 turbine files (.trb)

The turbine data files: CASENAME_###T11.trb and/or CASENAME_###Q11.trb could not be found.

The turbine data file is already in use by another turbine component.

The data in the turbine input file contains an error

The data in the turbine input file contains an error

Number of vanes used in turbine data file is greater than the maximum number of vanes allowed in WANDA (20).

Number of 'interpolation curves' used in the turbine data file is greater than the maximum number of 'interpolation curves' allowed in WANDA (20).

The initial control system value and the initial vane position specified by the user are different.

Only positive vane positions are allowed.

1.3 Examples

1.3.1 Model description

The following example is meant to explain the function of the turbine component. The turbine is placed between two reservoirs, as shown in Figure 1.3. As this example is an academical case, the pipeline systems at both sides of the turbine are neglected. However, in practical applications the influence of the pipeline should be considered (see example 2).

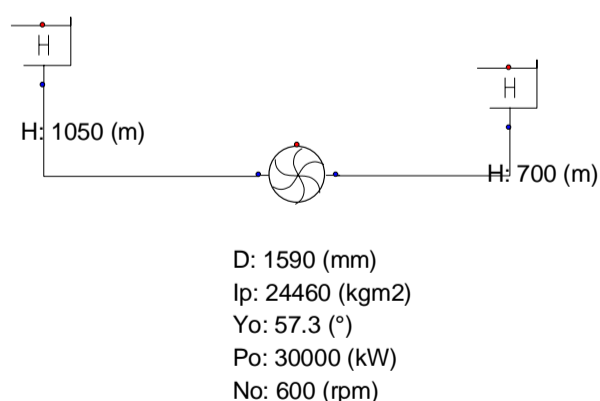


Figure 1.3: Wanda scheme.

The turbine interpolation curves are saved in the example files Turbine_001T11.trb and Turbine_001Q11.trb. Figure 1.4 presents a visual representation of these curves. In addition, the unit curves have been reconstructed from the interpolation curves and have also been added to the figure.

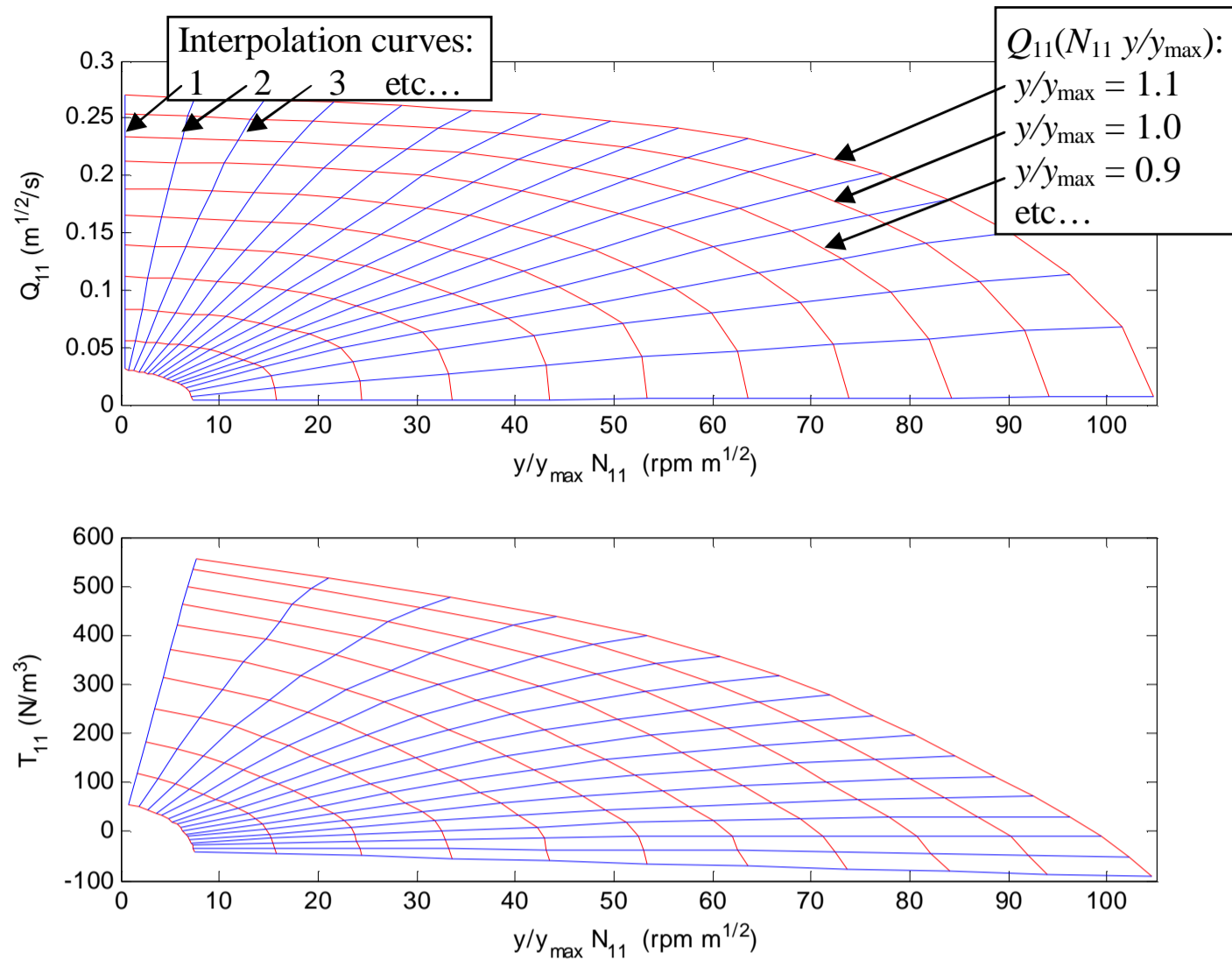
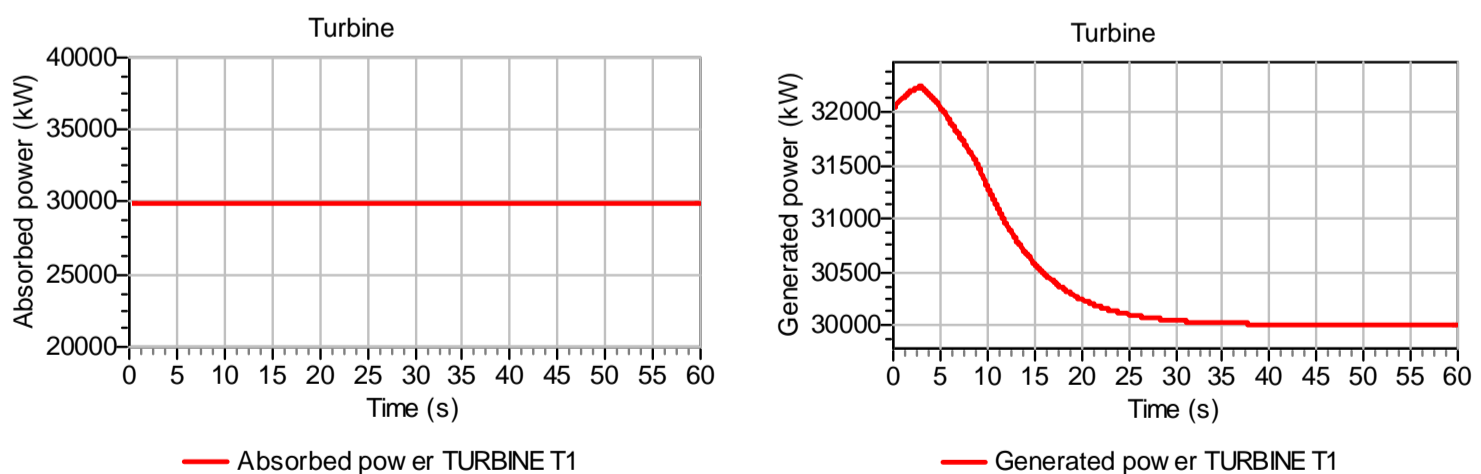


Figure 1.4: Turbine unit curves with interpolation curves (see example directory for the input files “Turbine_001T11.trb” and “Turbine_001Q11.trb”)

1.3.2 Finding the equilibrium speed for a specified P_{abs}

The following procedure can be followed to find the speed that places the generated power in equilibrium with the absorbed power: An initial speed equal to the rated speed is input (for this example 600 rpm) and a transient calculation performed without varying the hydraulic conditions, vane position or absorbed power. Figure 1.5 shows that the absorbed power and generated power are not in equilibrium with an initial speed of 600 rpm. For the next 35s the turbine speeds up in order to balance the absorbed and generated power. After 35s the turbine has reached an equilibrium with a speed of approximately 751.6 rpm. This equilibrium speed can be used in subsequent transient calculations, where the turbine is initially in equilibrium.



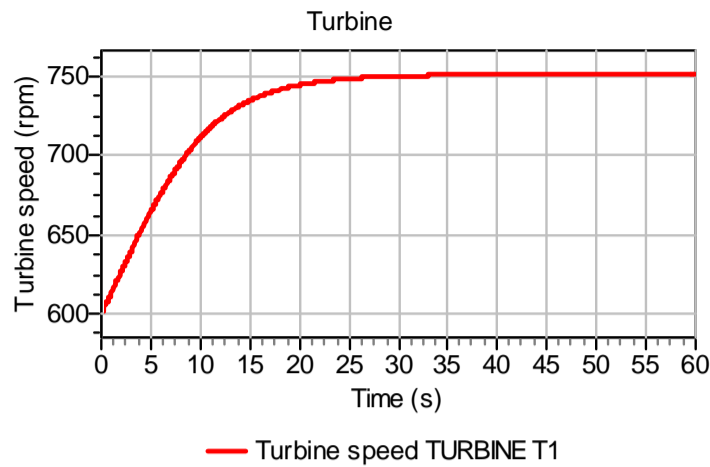


Figure 1.5. Turbine speed increases as power is not in equilibrium at $t=0s$.

1.3.3 Varying the absorbed power P_{abs}

At $t=0s$ there is an equilibrium between generated and absorbed power. The absorbed power is lowered from 30000 at $t=20s$ to 25000 kW at $t=40s$ (using the action table of the turbine). Due to the inertia of the turbine a disequilibrium will develop. The turbine will speed up in order to lower the generated power and to restore the equilibrium. Figure 1.6 shows the increase of the turbine speed at constant vane position.

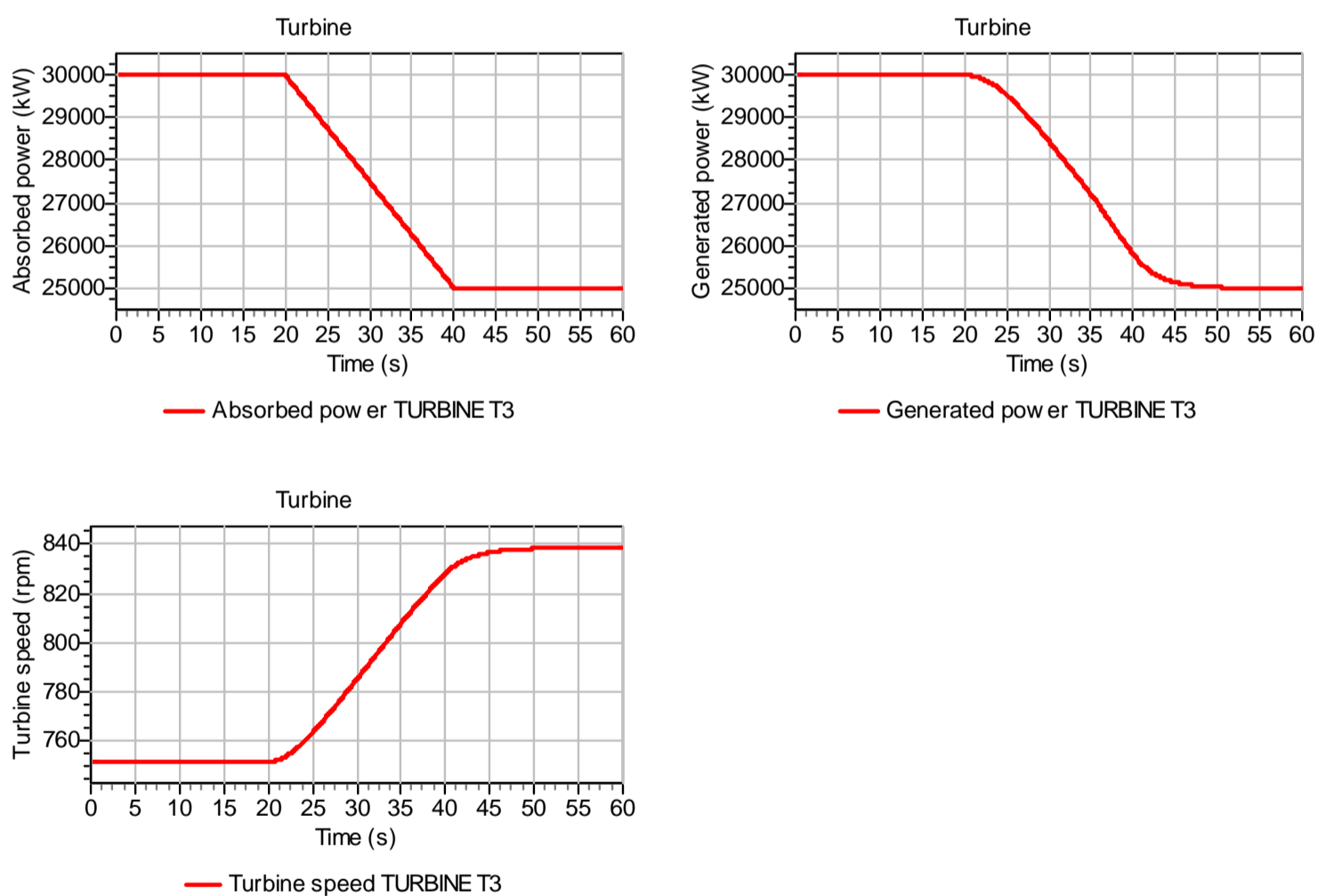


Figure 1.6. Decreasing power results in increasing turbine speed.

1.3.4 Varying the vane position

By changing the vane position, it is possible to control the speed of the turbine. A control signal line is connected to the turbine as shown in Figure 1.7. The signal decreases the vane position from 100% of the maximum angle at $t=5s$ to 95% at $t=25s$. For this example the absorbed power is kept constant ($P_{abs} = 30\,000$ kW).

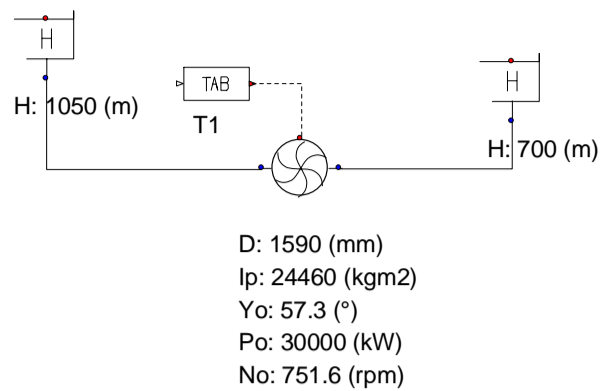


Figure 1.7. Wanda scheme and connection of signal line.

The system is in equilibrium at $t=0$ s. The discharge and generated power will decrease due to the decreasing vane position, as can be expected from the turbine unit curves (Figure 1.4). Figure 1.8 shows the generated power and the vane position. After $t=25$ s the vane position is kept constant.

Due to the imbalance between generated and absorbed power the speed of the turbine changes. Because the generated power is lower than the absorbed power, the speed of the turbine is decreasing according to equation (1.3). At $t=60$ s the turbine is in equilibrium again as the speed is constant and the generated power equals the absorbed power.

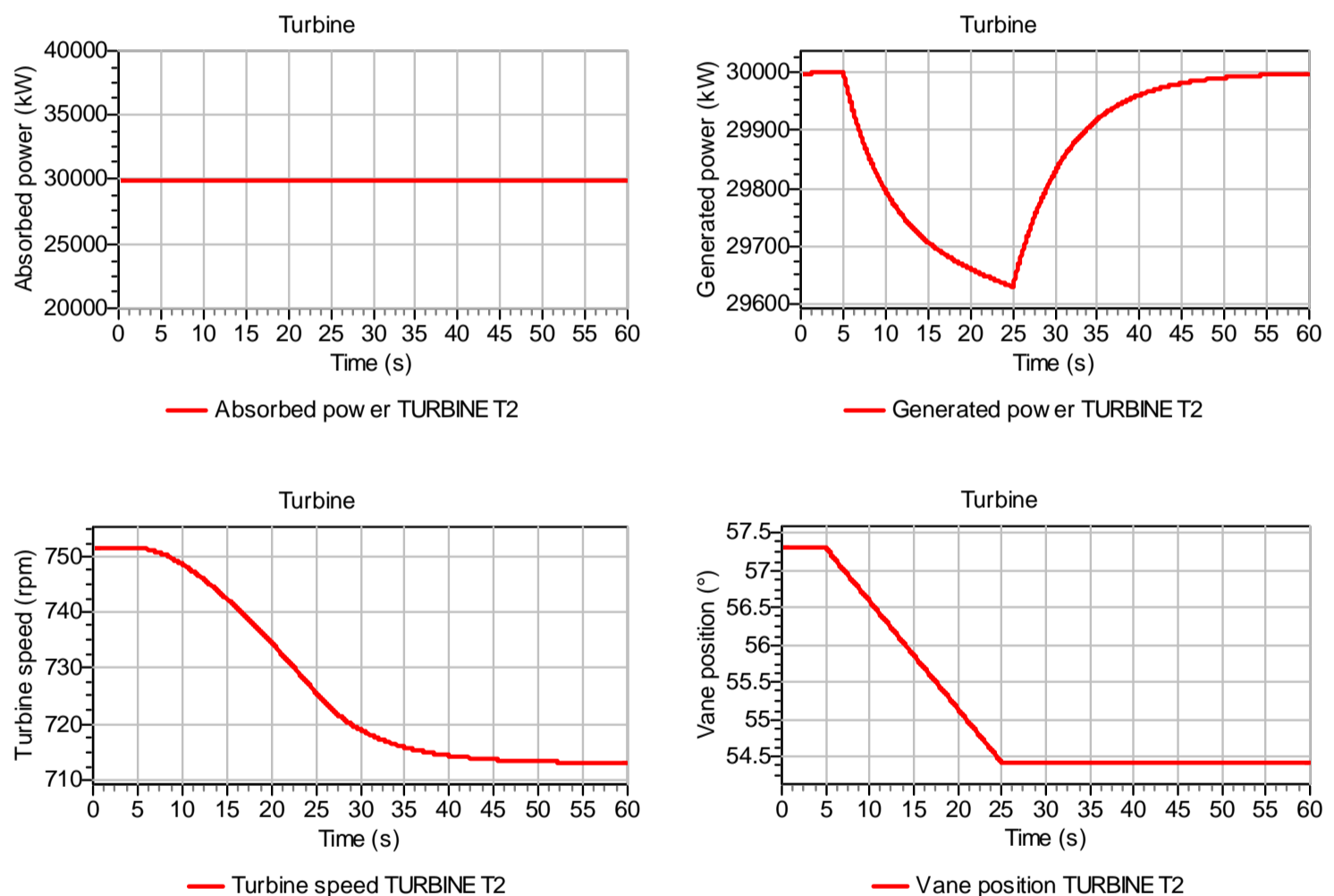


Figure 1.8. Changes in generated power due to reduced vane position.

1.3.5 More realistic example

To show the influence of the pipeline system on the turbine a more realistic case is included as well. Here the absorbed power is initially in equilibrium at 27970 kW. At $t=10$ s the absorbed power drops to 22000 kW at $t=30$ s. The vane position is reduced to prevent too high speed values. Since the change of vane position is a reaction to the drop in absorbed power, the vane position changes with a delay of 5 seconds from 100% (at $t=15$ s) to 76% (at $t=35$ s). Figure 1.9 shows the scheme for this example including the pipelines.

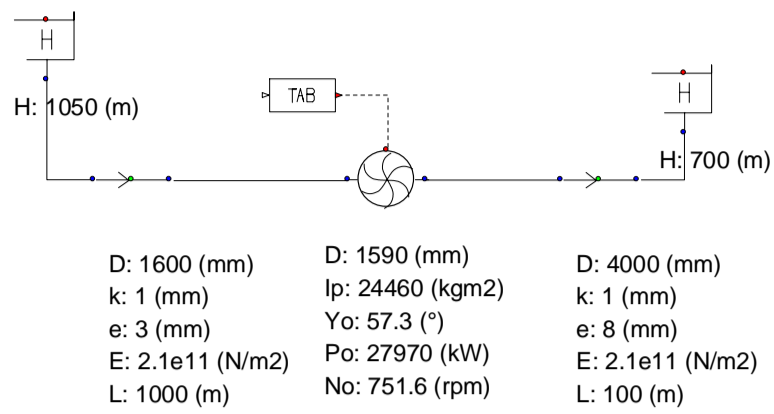


Figure 1.9: Wanda scheme



Figure 1.10: Input via action table (left) and control-table (right)

Figure 1.11 shows the change in power, speed and vane position. Due to the inertia there is a ‘overshoot’: the generated power drops below the equilibrium value when the absorbed power is kept constant again (at t=30s). At t=50 the system is in equilibrium again.

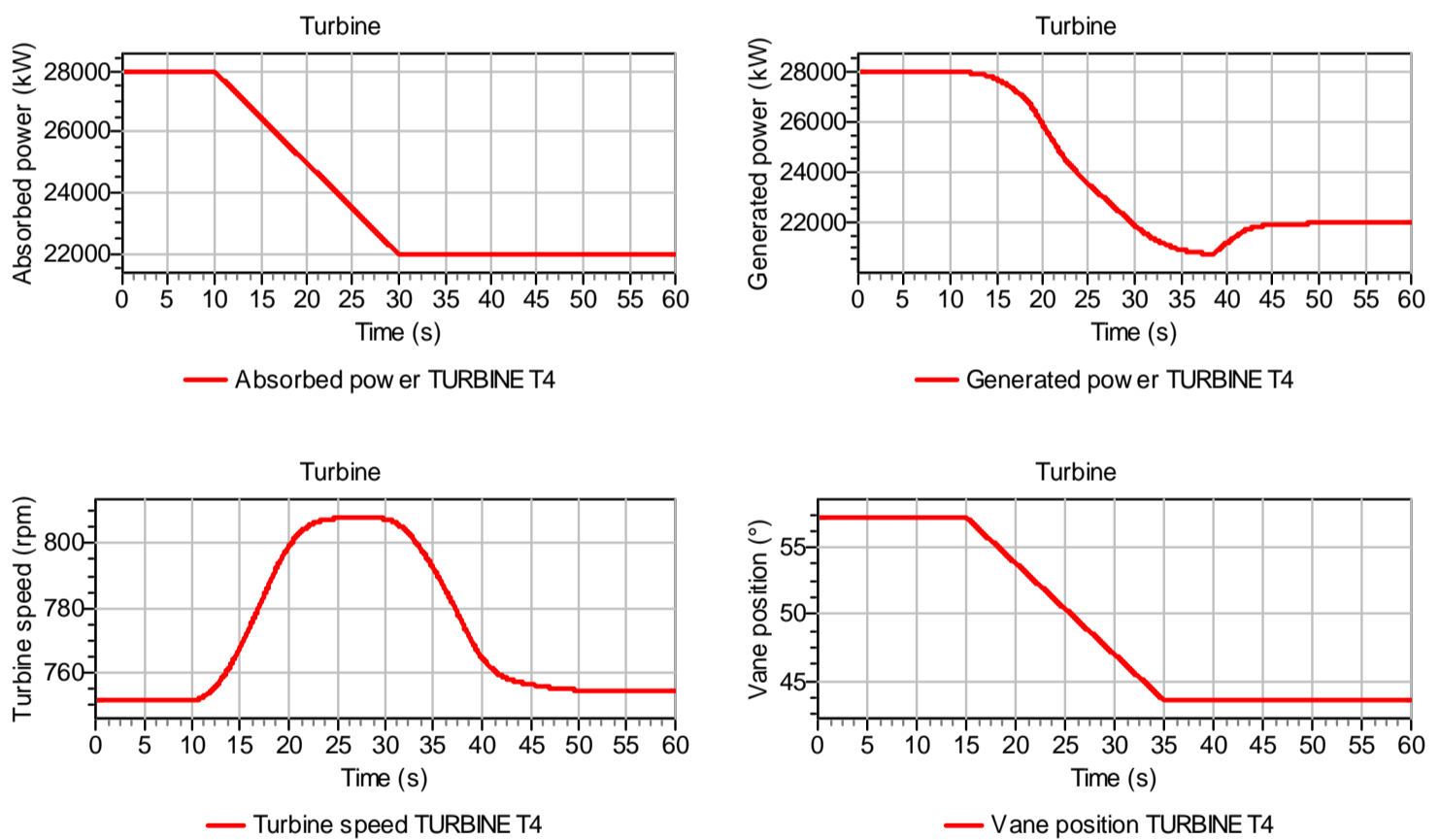


Figure 1.11: Power, speed and vane position