An Ensemble based Reliable Storm Surge Forecasting for Gulf of Mexico

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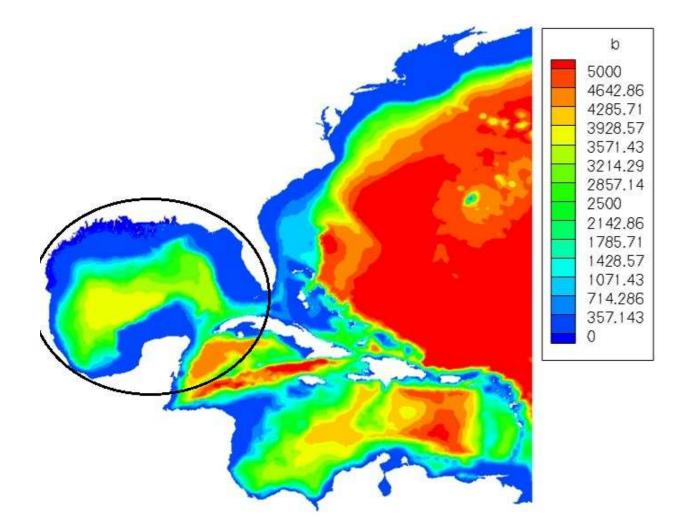
An Ensemble based Reliable Storm Surge Forecasting for Gulf of Mexico; Altaf U. et al., (slide 1)

- Background
- ADCIRC Model
- Kalman Filter
- Numerical Experiment
- Time Local Hinfinity Filter
- Conclusion

- Storm surge have recently seen an attention due to the devastating 2005 hurricane season.
- There have been substantial efforts to place instruments capable of measuring water levels, wind speeds, and wave heights particularly along the Texas, Louisiana and Mississippi coasts.
- These data collection efforts have been particularly useful for hindcasting recent hurricane events, for the purpose of better understanding the coastal impact, and designing improved coastal protection systems.
- Based on these studies and data a real-time forecasting system is developed.

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Background



North Atlantic

Bathymetry

Gulf of Mexico



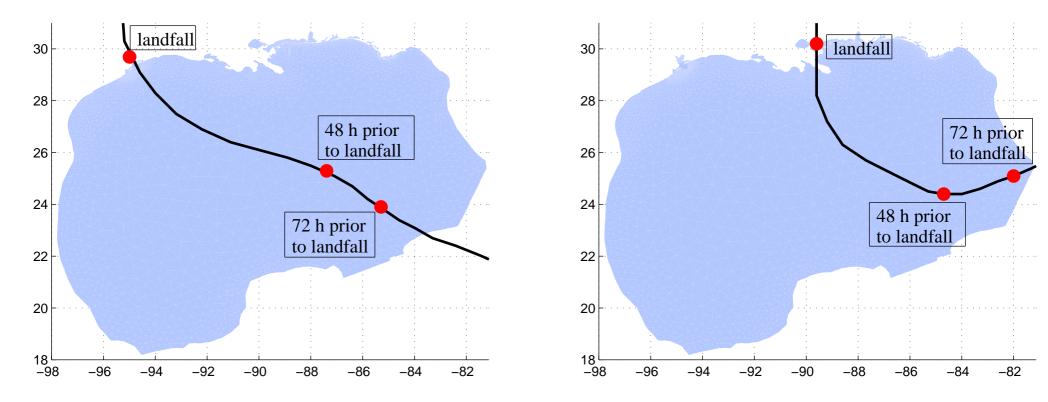
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- Advanced Circulation (ADCIRC) model the shallow water equations
- It uses finite element methods defined on unstructured meshes in space and difference schemes in time.
- Coupled with a wind-wave model for capturing wave-induced setup.
- Typical domain Gulf of Mexico possibly including the western north Atlantic
- Recently used for many hindcast studies of recent hurricanes.
- Aim to compute predicted water level along the coast within 1-2 hour time window.

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Hurricanes



- Left: Hurricane Ike. Landfall on Sept. 13, 2008 at 07:10 UTC and the locations of the hurricane approximately 48 and 72 h before landfall.
- Right: Hurricane Katrina. Landfall on Aug. 29, 2005 at 11:10 UTC and the locations of the hurricane approximately 48 and 72 h before landfall.

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• Example:

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	lke	Katrina
Domain	Western North Atlantic	Western North Atlantic
Avg. Mesh Element Size	1.34 km ²	1.34 km ²
Time Step	1 s	1 s
Wind Field	OWI	OWI
Nodes	3, 322, 439	5,035,113
CPUs	2038	2038

• Summary of hindcast (truth) simulation used for Hurricanes Ike and Katrina to generate data.

- The ADCIRC model has been used successfully in hindcast mode to study many Hurricanes (Betsy, Katrina, Rita, Gustav and Ike).
- This help developed very accurate descriptions of the Texas, Louisiana and Mississippi coasts, which include accurate bathymetries, coastal features.
- These hindcast models require highly resolved finite element meshes, $(10^7 10^8)$ and require small time steps to resolve wetting and drying fronts.
- running hindcast in forecast thus require significant computational resources just to run one forecast.
- The goal is clear: To improve storm surge forecasts by a data assimilation using only a small ensemble of states on a coarser grid.

Model:
$$\mathbf{x}_{k+1} = \mathcal{M}_k(\mathbf{x}_k) + \mathbf{u}_k$$

Observation model:

$$\mathbf{y}_{k}=\mathcal{H}_{k}\left(\mathbf{x}_{k}\right)+\mathbf{v}_{k}$$

• Prediction step

$$\mathbf{x}_{k}^{b} = \mathbf{M}_{k} \mathbf{x}_{k-1}^{a} \tag{1}$$

$$\mathbf{P}_{k}^{b} = \mathbf{M}_{k} \mathbf{P}_{k-1}^{a} \mathbf{M}_{k}^{T} + \mathbf{Q}_{k-1}$$
(2)

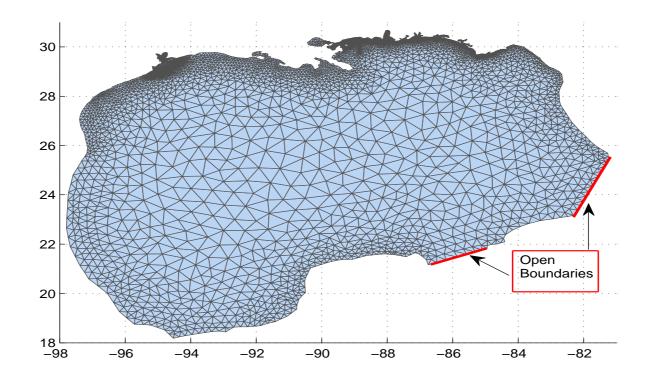
• Update:

$$\mathbf{K}_{k} = \mathbf{P}_{k}^{b} \mathbf{H}_{k}^{T} (\mathbf{H}_{k} \mathbf{P}_{k}^{b} \mathbf{H}_{k}^{T} + \mathbf{R}_{k})^{-1}$$
(3)
$$\mathbf{x}_{k}^{a} = \mathbf{x}_{k}^{b} + \mathbf{K}_{k} (\mathbf{y}_{k} - \mathbf{H}_{k} \mathbf{x}_{k}^{b})$$
(4)
$$\mathbf{P}_{k}^{a} = \mathbf{P}_{k}^{b} - \mathbf{K}_{k} \mathbf{H}_{k} \mathbf{P}_{k}^{b}$$
(5)

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The Experimental Setup

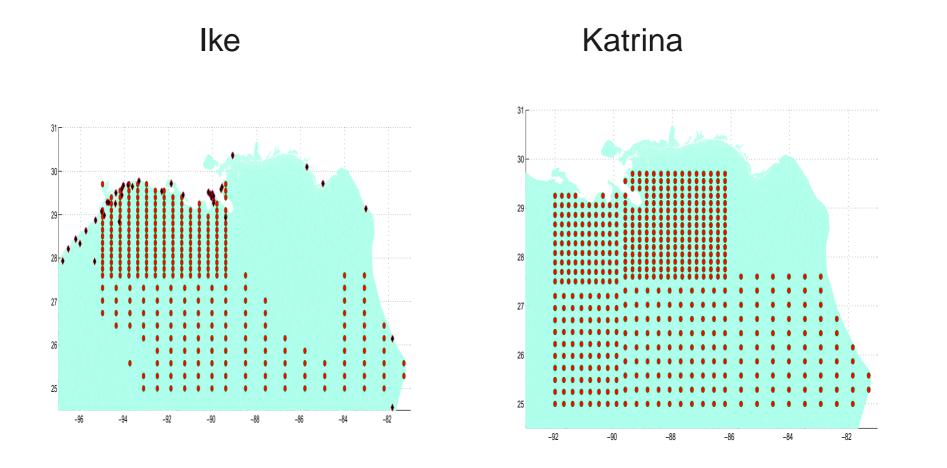


- Discretization of the Gulf of Mexico domain containing 8006 nodes and 14, 269 elements.
- The open boundaries are forced by the 5 tidal constituents: K1, O1, P1, M2, and S2.
- timestep 10s

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The Experimental Setup



371 observation stations

• Assimilation step: 2h

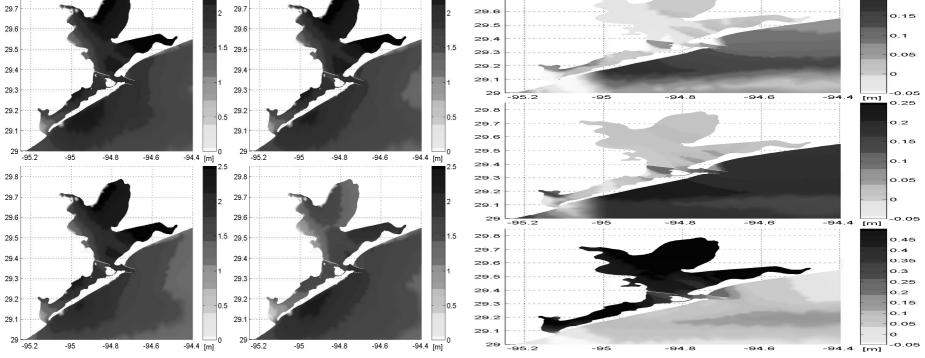
Ensembles: 10

559 observation stations



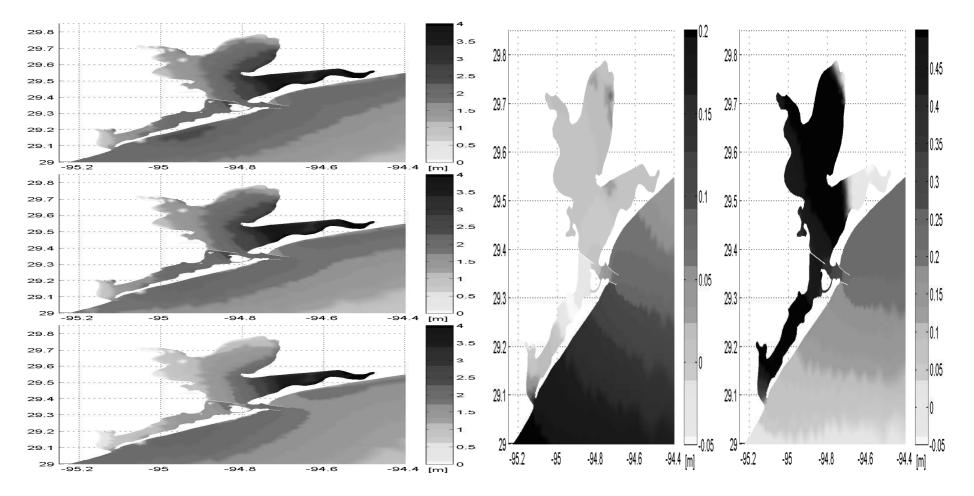
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	Simulation	Coastal RMS-Error	RMS-Error for Surge > 3 m
	ISim-ND	1.92	1.91
	ISim-48	1.86	1.81
	ISim-24	1.82	1.80
	ISim-FD	1.65	1.62
29.8		2.5 29.8	
29.7 29.6		2 29.7 29.6 25	0.1
29.5		1.5 29.5 29.4 29.4	
29.4			



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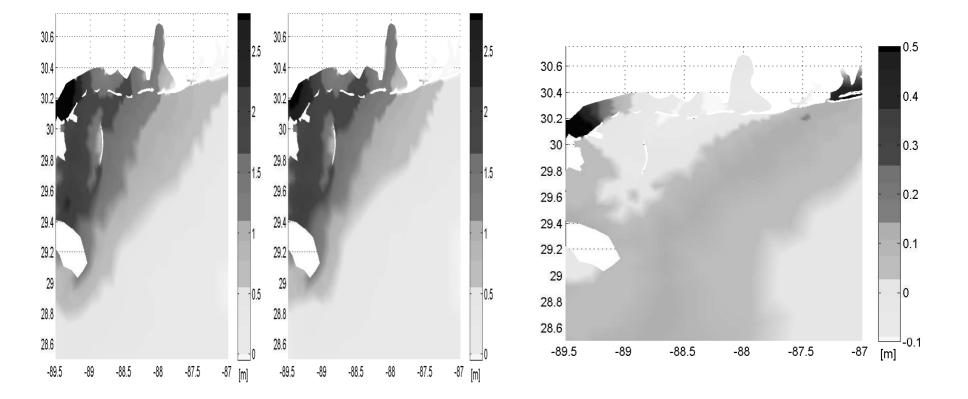
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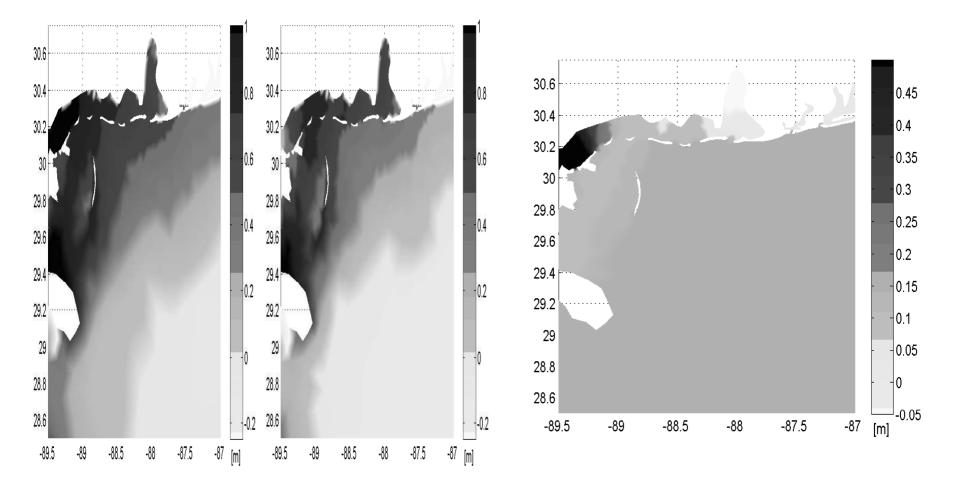
• Free surface elevation error on Sept. 13, 2008, at 07:00 UTC, from truth for ISim-ND (top), ISim-24 (middle), and ISim-FD (bottom).

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Simulation	RMS-Error for Surge > 4 m	RMS-Error for Surge > 5 m
KSim-ND	2.43	2.94
KSim-36	2.03	2.48
KSim-24	1.99	2.48
KSim-FD	1.92	1.89



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• Free surface elevation error on August. 29, 2005, before Landfall, from truth for ISim-ND (top), and ISim-FD (bottom).

Model:
$$\mathbf{x}_{k+1} = \mathcal{M}_k(\mathbf{x}_k) + \mathbf{u}_k$$

Observation model: y

$$\mathbf{y}_{k}=\mathcal{H}_{k}\left(\mathbf{x}_{k}\right)+\mathbf{v}_{k}$$

• Prediction step

$$\mathbf{x}_{k}^{b} = \mathbf{M}_{k} \mathbf{x}_{k-1}^{a} \tag{6}$$

$$\triangle_k^b = \mathbf{M}_k \triangle_{k-1}^a \mathbf{M}_k^T + \mathbf{Q}_{k-1}$$
(7)

• Update:

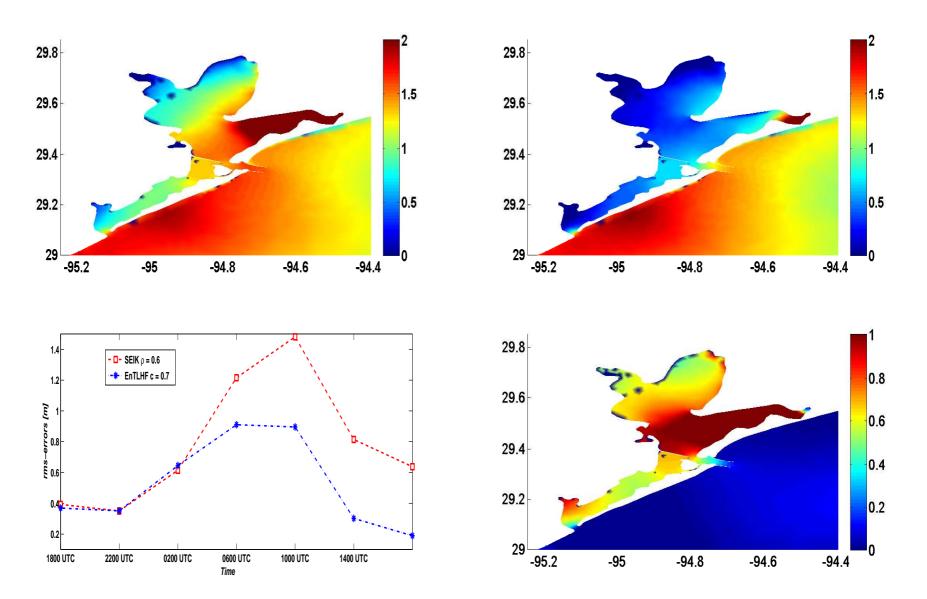
$$\mathbf{x}_{k}^{a} = \mathbf{x}_{k}^{b} + \mathbf{K}_{k}(\mathbf{y}_{k} - \mathbf{H}_{k}\mathbf{x}_{k}^{b})$$
(8)

$$\mathbf{K}_{k} = \triangle_{k}^{a} \mathbf{H}_{k}^{\prime} \mathbf{R}_{k}^{-1}$$
(9)

$$(\triangle_k^a)^{-1} = (\triangle_k^b)^{-1} + \mathbf{H}_k^T \mathbf{R}_k^{-1} \mathbf{H}_k - \gamma_k \mathbf{L}_k^T \mathbf{S}_k \mathbf{L}_k$$
(10)

	Simulation	Coastal RMS-Error	RMS-Error for Surge > 3 m
	ISim-ND	1.92	1.91
	SEIK	1.62	1.65
	H_∞	0.80	0.87
29.8 29.6 29.4 29.2 29.2		23.8 29.6 29.6 29.4 29.4 29.4 29.4 29.2 29.4 29.4 29.4	34.6 34.4 29.8 29.8 29.8 29.8 29.8 29.6
	EnKF	TLHF	Difference

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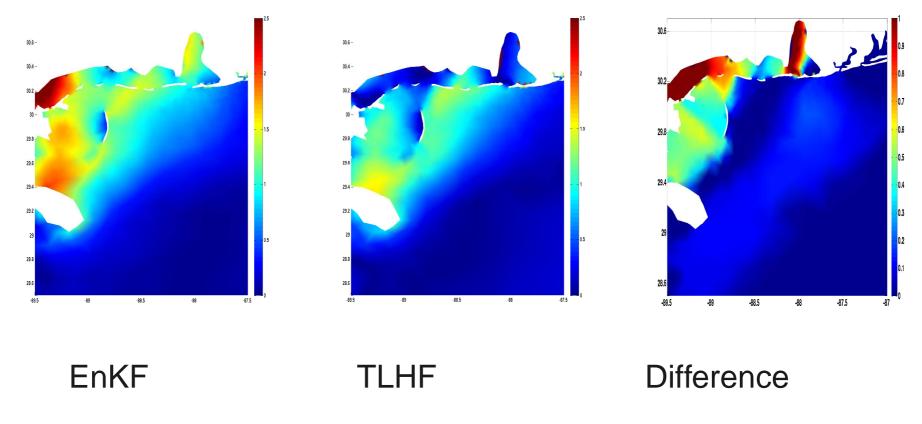


• Top: Free surface elevation error on Sept. 13, 2008, before Landfall.

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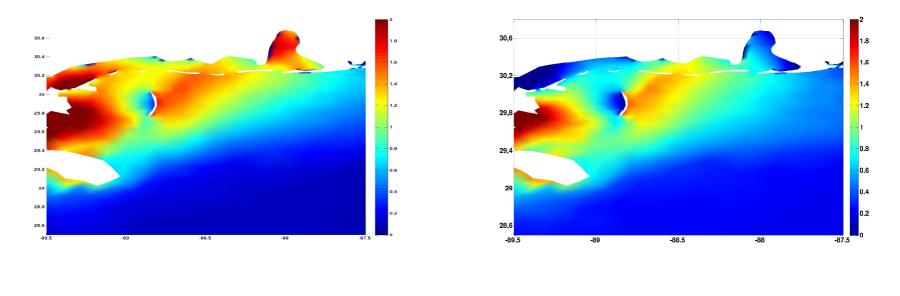
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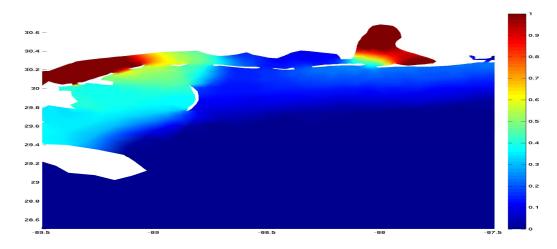
Simulation	RMS-Error for Surge $> 4 \text{ m}$	RMS-Error for Surge $> 5 \text{ m}$
ISim-ND	2.38	2.87
SEIK	1.92	1.89
H_{∞}	0.72	0.45





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• Top: Free surface elevation error on August. 29, 2005, at Landfall.

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- Successfully implemented and tested DA methodology within AD-CIRC model.
- Ensemble based Kalman filtering shows underestimation.
- Ensemble based H_{∞} filtering shows significant improvements to EnKF.
- Lots need to be done for an operational storm surge system.
- References:

Butler et. al 2012, Data assimilation within the framework of Advanced Circulation Model., Monthly Weather Review. Altaf et. al 2012, An Ensemble based time-local H_{∞} filter for reliable storm surge forecasting, Computer and Geosciences



Future of Data Assimilation is



THANK YOU



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