# Vatlestraumen tidal current - Characterization of local transport properties

### Tomas Torsvik

Wave Engineering Laboratory Institute of Cybernetics at Tallinn University of Technology

In collaboration with: Gunnar Furnes and Helge Avlesen, Uni Research, Norway Armin Pobitzer, Institute of Informatics, UiB, Norway

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JONSMOD 2012 1/15 Background:

The rock fallpipe ship MV Rocknes capsized after grounding in Vatlestraumen south-west of Bergen on 19 January 2004.

- Rocknes carried a total of 470 m<sup>3</sup> heavy bunker fuel and 70 m<sup>3</sup> marine diesel, most of which was released during the first days after capsizing.
- A total of 45 km of shoreline was significantly contaminated by the oil spill.
- Strong tidal currents believed to be a significant factor in the grounding incident and oil spill dynamics.
- Original motivation:
  - provide information on strength and spatial variation of tidal current in connection with trail process following the accident.

Extended study:

- oil spill test case for Lagrangian trajectory model
- identification of coherent flow structures





Source: "ROCKNES"-ULYKKEN, The Norwegian Coastal Administration, 23. november 2004

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### Model area - Vatlestraumen



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# Model area - Vatlestraumen



Topography of model area

Detailed view of topography in Vatlestraumen

- Low resolution simulations: 80 m horizontal grid resolution, 10 sigma layers
- High resolution simulations: 20 m horizontal grid resolution, 31 sigma layers
- Bergen Ocean Model (BOM)
  - Numerical terrain-following 3D hydrodynamical model
  - Non-hydrostatic model equations; parallel code

# Tidal current measurements

Data from Aanderaa instruments measurement site in Vatlestraumen



Measurements show tidal water level change of about 1.2 m. Tidal water level change at the time of the accident is believed to be slightly less than 1 m.



Current velocity measurements at surface (blue), 4 m depth (magenta) and 8 m depth (orange). Surface velocity data are probably wrong. Current speed measurements at 8 m depth regularly reach 0.8 m/s, with peaks exceeding 1 m/s.

#### Current speed 2010-03-04

Maximum northward current occurs approximately 1.5 hours after lowest tide.

### Simulated current and water level



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# Simulated depth-mean current in Vatlestraumen

- Simulation forced with tide, water level and phase, through north and south boundaries
- no wind forcing
- Model spin up time: 24 hours



Depth-mean current 2004-01-19 at 16:00



Depth-mean current 2004-01-19 at 17:00

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Figures show the depth-mean current in Vatlestraumen around the time of the accident.

- Maximum flow velocity: 1.6 m/s

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#### Particle tracking model

$$\begin{bmatrix} x(t_n) \\ y(t_n) \\ z(t_n) \end{bmatrix} = \begin{bmatrix} x(t_{n+1}) \\ y(t_{n+1}) \\ z(t_{n+1}) \end{bmatrix} + \begin{bmatrix} U(t_{n-1}) + \frac{\partial A_H}{\partial x} \\ V(t_{n-1}) + \frac{\partial A_H}{\partial y} \\ W(t_{n-1}) + \frac{\partial K_H}{\partial z} \end{bmatrix} \Delta t + \begin{bmatrix} \sqrt{2A_H}\gamma_1 \\ \sqrt{2A_H}\gamma_2 \\ \sqrt{2K_H}\gamma_3 \end{bmatrix} \sqrt{\Delta t}$$

(x, y, z)Position of particle at time t (stochastic variable)(U, V, W)Fluid velocity at (x, y, z) $\Delta t$ Discrete time step $A_H, K_H$ Eddy diffusion coefficient (horizontal,vertical) $\gamma_1, \gamma_2, \gamma_3$  $\sim N(0, 1)$ Particle tracking model run on-line with BOM, as an internal module.

# "Oil spill" transport by particle tracking

Simulation with 5000 particles, seeded at 3 m depth

Constant horizontal eddy diffusion coefficients

$$A_H = 0.1 m^2/s$$
  $K_H = 0 m^2/s$ 



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### Extent of oil spill, January 20, 9:45 am



Source: "ROCKNES"-ULYKKEN, The Norwegian Coastal Administration, 23. november 2004 ( 7)

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## **Okubo-Weiss parameter**

Okubo-Weiss parameter

$$W = s_n^2 + s_s^2 - \omega^2$$

where



- Analysis of output velocity fields from BOM.
- Provides an instantaneous measure for the relative contribution of deformation and vorticity.

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### OW-parameter over 6 hours



Results for 80 m horizontal grid resolution. 26 hours Okubo-Weiss parameter: dx = 80 m - 1

10000

8000

6000

4000

2000

0 2000 4000 6000 8000

length [m]







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ength [m]

4000

2000

0 2000 4000 6000 8000

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# Finite Time Lyapunov Exponents (FTLE)

Measure based on stretching between neighboring particles.

Theory based on the (right) Cauchy-Green deformation tensor

$$\mathbf{C}_{t_0}^{t_0+\tau}(\mathbf{x_0}) = \left[\frac{\partial \mathbf{x}(\mathbf{x_0}, t_0, t_0 + \tau)}{\partial \mathbf{x_0}}\right]^T \left[\frac{\partial \mathbf{x}(\mathbf{x_0}, t_0, t_0 + \tau)}{\partial \mathbf{x_0}}\right]$$

maximum FTLE

$$\text{FTLE}_{\tau}(\mathbf{x_0}) = \frac{1}{\tau} \ln \sqrt{\lambda_{\max}\left(\mathbf{C}_{t_0}^{t_0 + \tau}\right)}$$

where  $\lambda_{\max}\left(\mathbf{C}_{t_0}^{t_0+ au}\right)$  is the maximum eigenvalue of  $\mathbf{C}_{t_0}^{t_0+ au}$ 

- Practical calculation based on largest increase in separation distance between particles in a cloud during some time window τ.
- Ridges of FTLE indicate lines of flow separation, similar to separatrices of vector field topology.
- Results for FTLE obtained by off-line trajectory model, using time window  $\tau = 30$  min.

### FTLE over 6 hours

25 hours



28 hours



26 hours



29 hours



27 hours



30 hours



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- Both methods identify regions of high dynamic variability.
- The dynamically active and passive regions identified by the Okubo-Weiss parameter and FTLE match well with behavior of Lagrangian particles.

#### Okubo-Weiss

- Easy to compute. Only the Eulerian hydrodynamic model is required.
- Regions of high strain and high relative vorticity are almost stationary throughout the tidal cycle.

FTLE

- Requires an additional model for computing of Lagrangian trajectories.
- Reveals Lagrangian coherent structures which display significant variability over a tidal cycle.

### Thank you for your attention!