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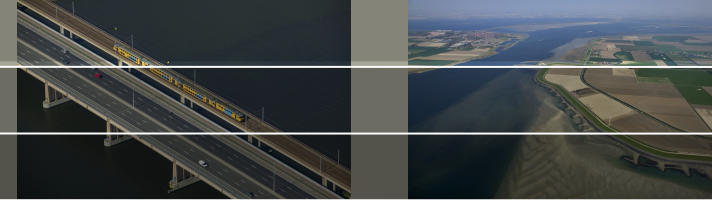
# Calibration in OpenDA

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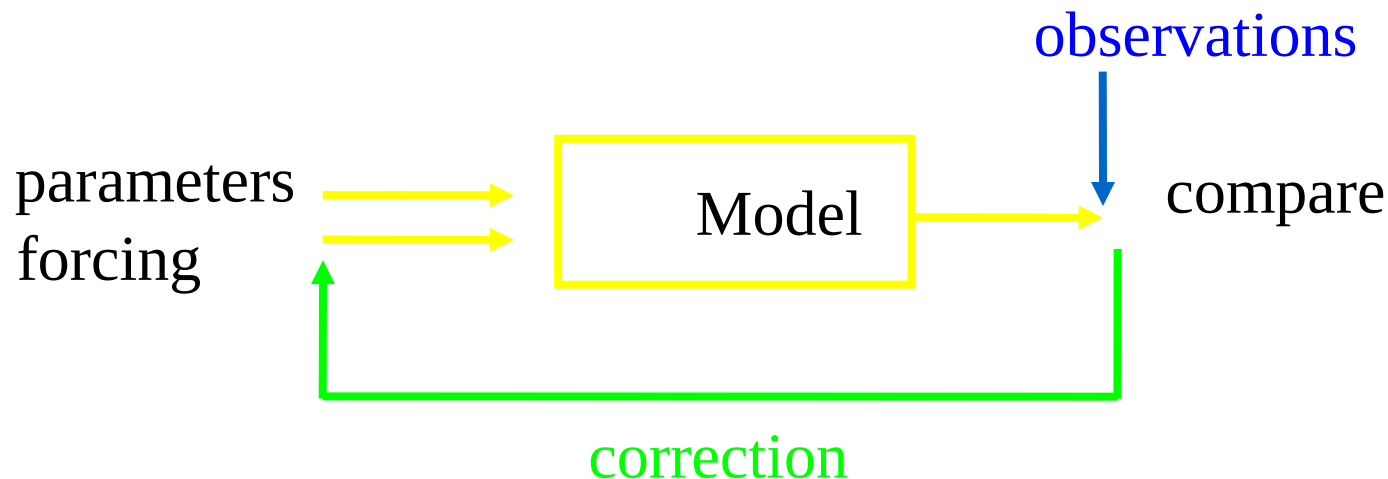
# Outline

- **Introduction**
- **Minimization of distance to observations**
- **Regularization**
- **Optimization**
- **Algorithms**
- **Example**
- **Options**

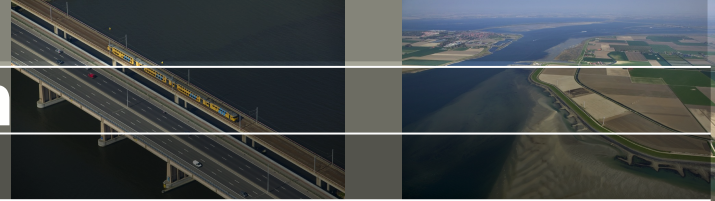
# Calibration



- Many models contain uncertain parameters, often related to friction, boundary conditions or sub-soil material properties
- Model output can be validated against observations.



# Optimization of a costfunction



- calibration is defined as an optimization problem
- elaborate background in statistics, e.g. log-likelihood function

$$\min_{p,x(0),w(t)} J = \min_{p,x(0),w(t)} J_o + J_p + J_i + J_s$$

- measure distance or misfit of model to observations
- depends on uncertainty of observations and representativeness

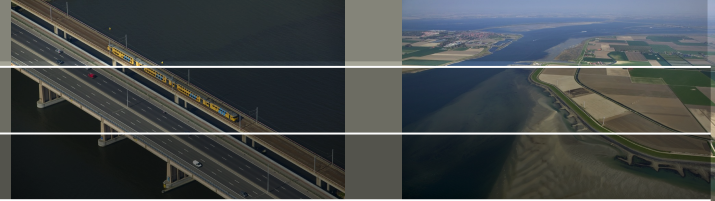
$$J_o = \sum (y_o(t) - Hx(t))' R^{-1} (y_o(t) - Hx(t))$$

- for independent observation errors

$$J_p = \sum_t \frac{(y_o(t) - y_m(t))^2}{\sigma_o^2}$$

- may be ill posed!

# Background terms



- often regularization is needed to obtain a well-posed problem
- a background error (Bayesian prior) solves this formally (and sometimes/often also practically)

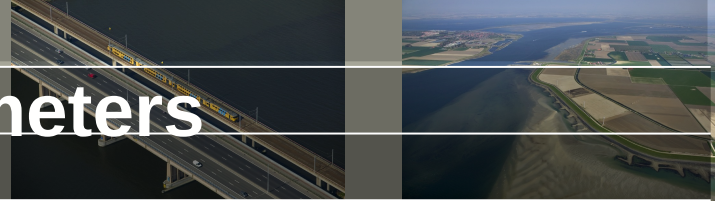
$$J_p = (p - p_0)' P_p^{-1} (p - p_0)$$

- this denotes a distance to the prior estimate, e.g. for independent errors for the parameters

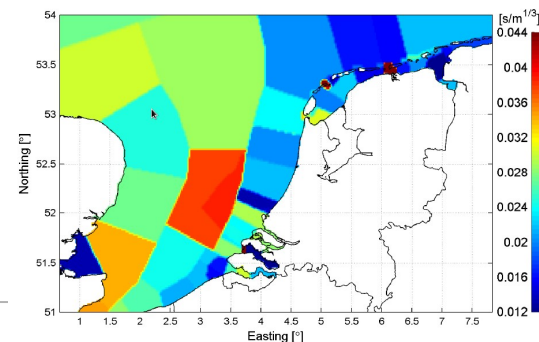
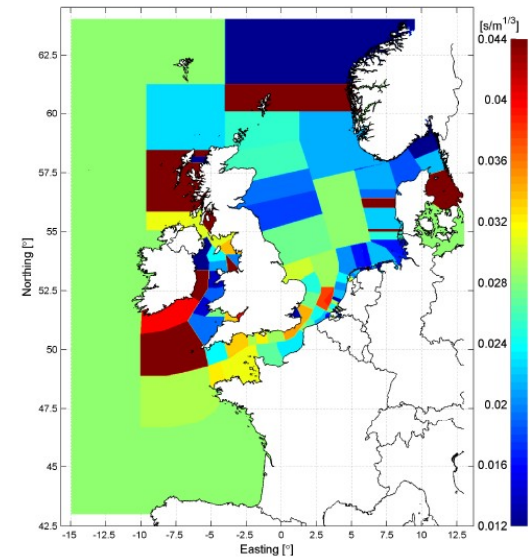
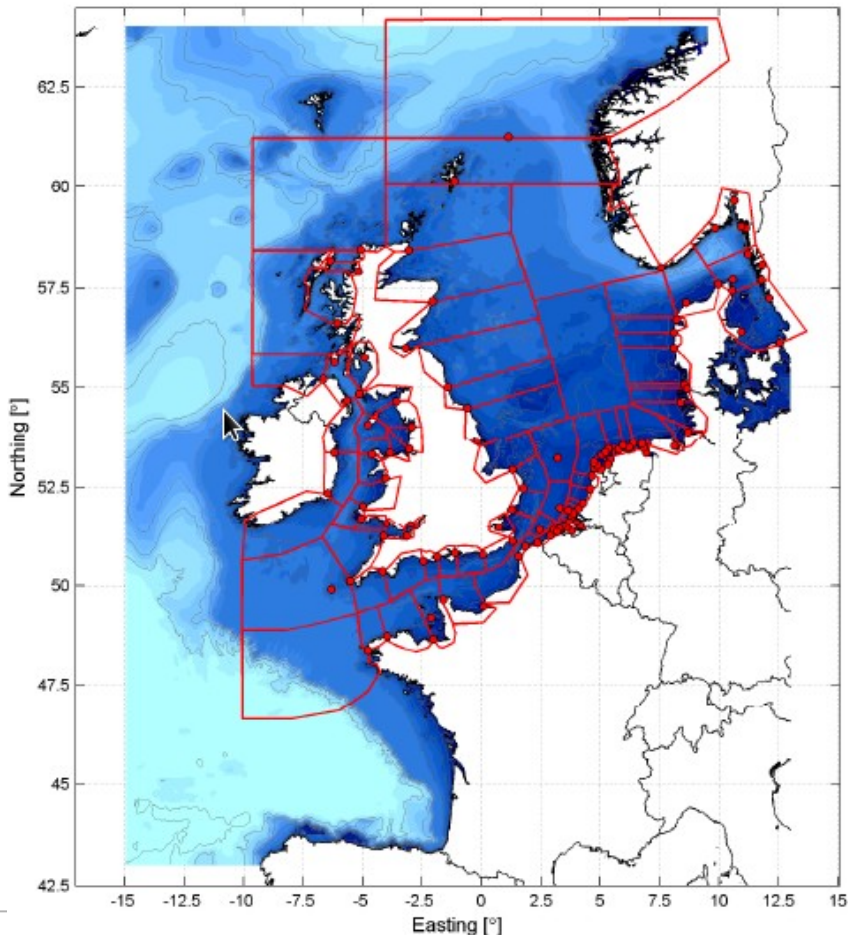
$$J_p = \frac{(p - p_0)^2}{\sigma_p^2}$$

- can also be used as a constraint on smoothness
- there is a mathematical theorem relating smoothness of the solution to the covariance of the errors

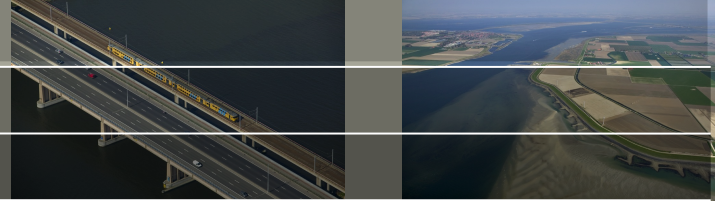
# Reduction of number of parameters



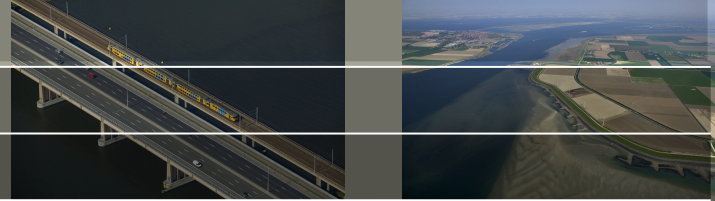
- there is a limit to what can be extracted from observations
- remember : number of parameters < independent observations
- useful: common sense, knowledge about the application



# Optimization algorithms



- Dud
  - Efficient for nearly linear models
- Sparse Dud
  - More efficient than Dud when one parameter influences only few observations
- Simplex
  - Robust generic method
- Powell
  - Can be efficient for finding last decimals of solution
- Gridded Full Search
  - Useful for testing
- GLUE, SCE
  - Can handle local optima
- Conjugate gradient
- LBFGS
- SPSA (under construction)

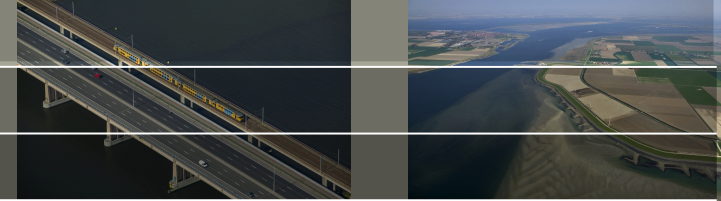


## **Does not Use Derivatives (DUD)**

- **Start running first guess and modifying each parameter**
- **Linearize the model around these values**
- **Solve linear problem**
- **IF**  
    **this is an improvement update linearization with new point (remove worst estimate from the list)**
- **ELSE**  
    **do a line-search (only until there is improvement)**



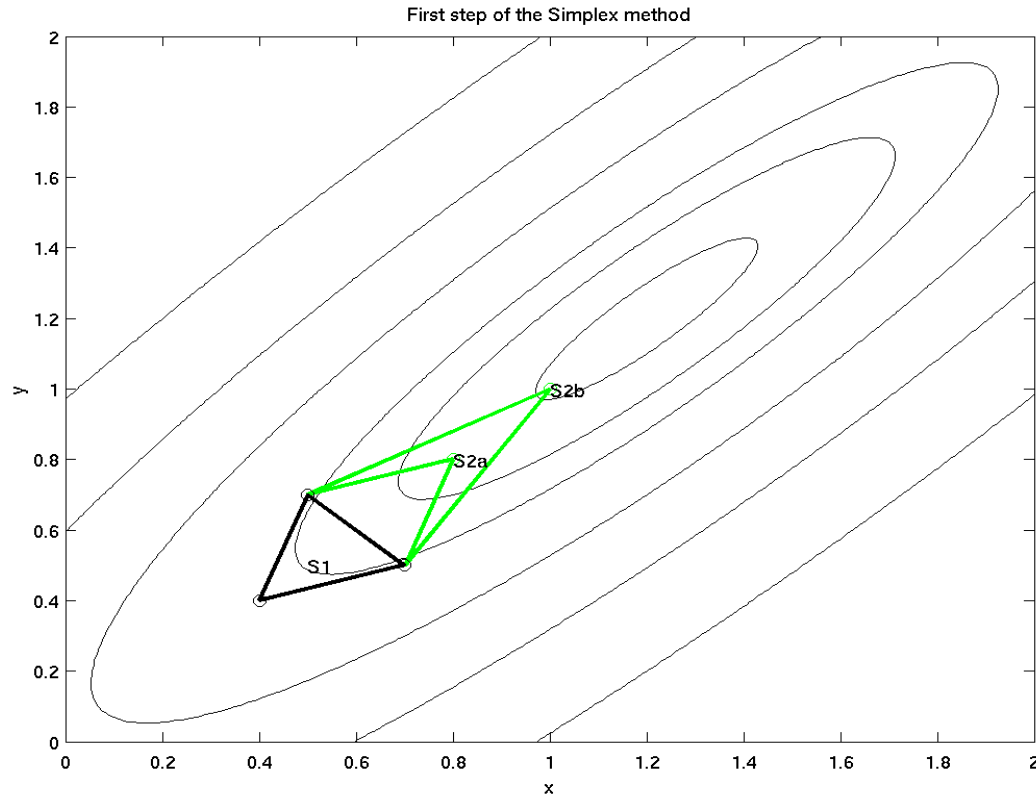
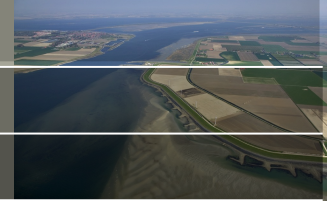
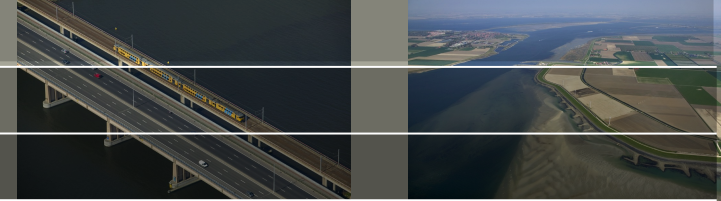
# DUD input file



```
<?xml version="1.0" encoding="UTF-8"?>
<DudConfig xmlns="http://www.openda.org" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:schemaLocation="http://www.openda.org
>
  <costFunction weakParameterConstraint="false" class="org.openda.algorithms.SimulationKwadraticCostFunction" factor="1.0"/>
>
  <outerLoop maxIterations="10" absTolerance="0.01" relTolerance="0.01" relToleranceLinearCost="0.001"/>
>
  <lineSearch maxIterations="5" maxRelStepSize="10.0">
>
    <backTracking shorteningFactor="0.5" startIterationNegativeLook="3"/>
>
  </lineSearch>
>
  <!-- optional additional criteria for stopping the calibration -->
>
  <stopCriteria>
>
    <stopCriterion class="org.openda.algorithms.AbsoluteAveragePerLocationStopCriterion" threshold="1.0E-5"/>
>
  </stopCriteria>
</DudConfig>
```

- Outer iterations can stop on various criteria
- WeakParameterConstraint adds term for difference to initial pars
- LineSearch starts when linear fit fails (look at output!)
- Use documentation or xml-editor that supports xml-schemas for assistance

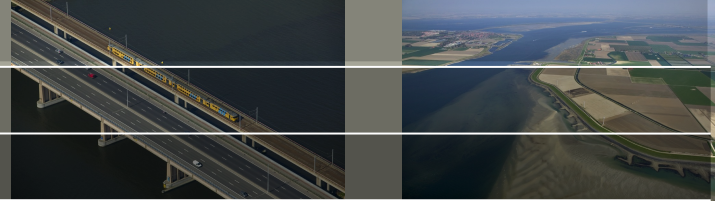
# Optimization methods



## Simplex

- try mirror point with largest value
- try to extend
- ...

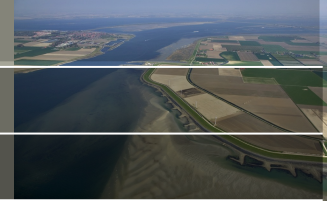
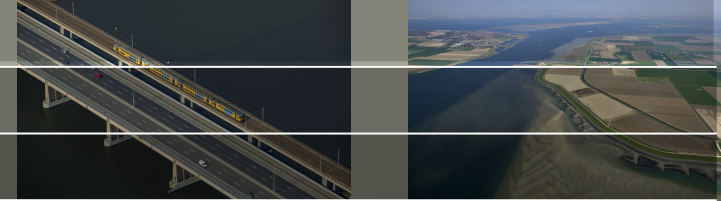
# Simplex input



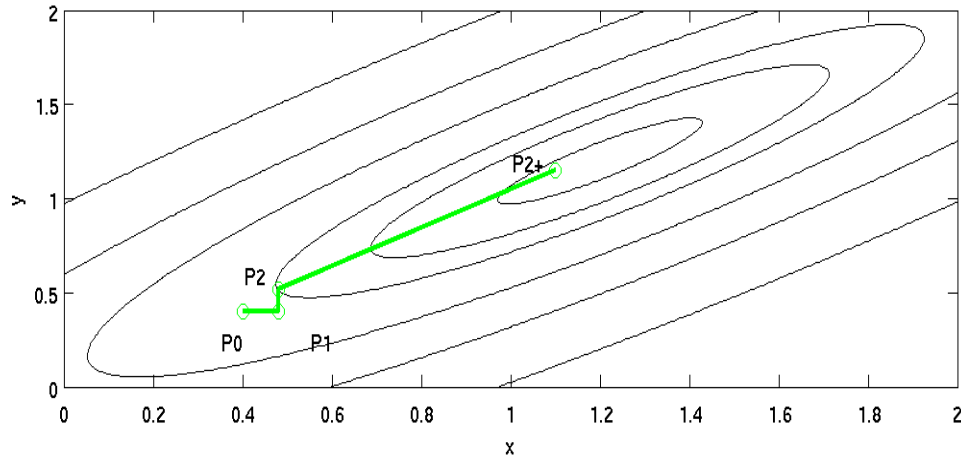
```
<SimplexConfig xmlns="http://www.opendata.org" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:schemaLocation="http://www.opendata.org/2012/01/SimplexConfig.xsd" >
  <costFunction weakParameterConstraint="false" class="org.opendata.algorithms.SimulationKwadraticCostFunction" factor="0.5"/>
  <outerLoop maxIterations="20" absTolerance="0.01" relTolerance="0.01"/>
  <!-- optional additional criteria for stopping the calibration -->
  <stopCriteria>
    <stopCriterion class="org.opendata.algorithms.AbsoluteAveragePerLocationStopCriterion" threshold="1.0E-5"/>
  </stopCriteria>
</SimplexConfig>
```

- Simplex has only outer iterations
- Standard stopCriteria test for changes to cost value

# Optimization methods

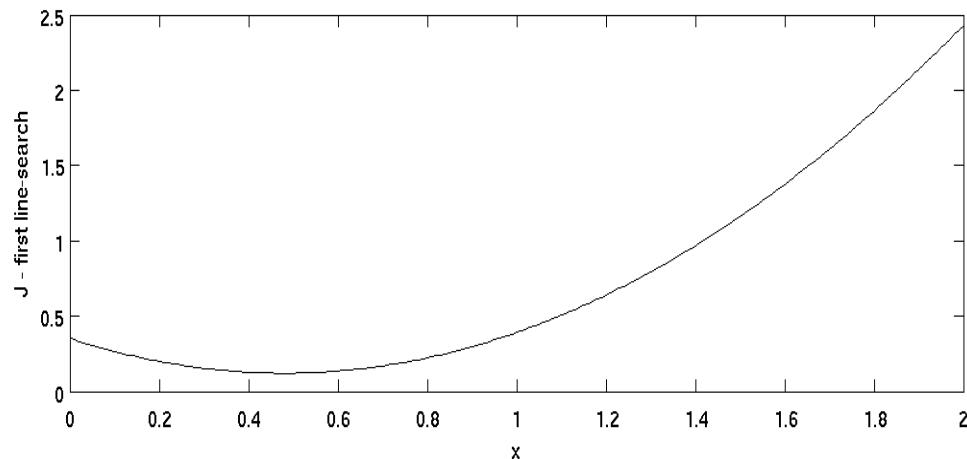


First step of the Simplex method

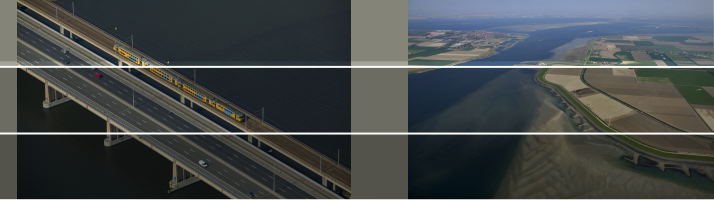


## Powell

- one line-search per parameter each outer iteration
- update search directions



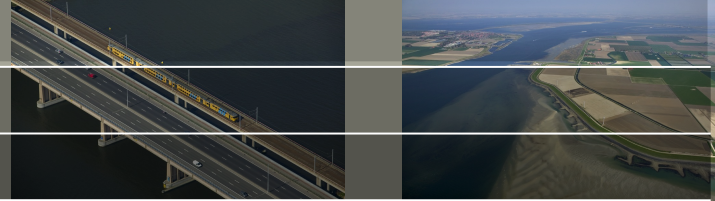
# Powell input



```
<PowellConfig xmlns="http://www.opendata.org" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:schemaLocation="http://www.opendata.org/2001/XMLSchema http://www.opendata.org/2001/XMLSchema.xsd">
  <costFunction weakParameterConstraint="false" class="org.opendata.algorithms.SimulationKwadraticCostFunction" factor="0.5"/>
  <outerLoop maxIterations="10" absTolerance="0.01" relTolerance="0.01"/>
  <lineSearch type="brent" maxIterations="10" relTolerance="0.01" maxRelStepSize="100.0">
    <brent startBracketValue="1.0"/>
  </lineSearch>
  <!-- optional additional criteria for stopping the calibration -->
  <stopCriteria>
    <stopCriterion class="org.opendata.algorithms.AbsoluteAveragePerLocationStopCriterion" threshold="1.0E-5"/>
  </stopCriteria>
</PowellConfig>
```

- Powell performs a series of line-searches
- Each line-search:
  - Bracket one lower cost between two larger ones
  - Followed by a series of parabolic fits
  - Initial line-searches change one parameter
  - Later line-searches use an estimate of the Hessian (Quadratic fit)

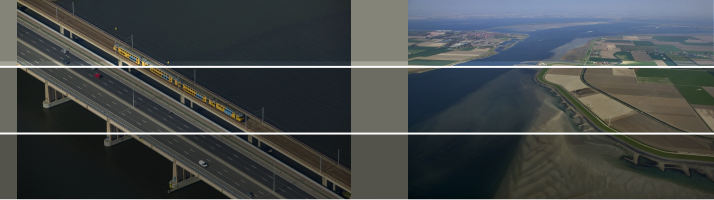
# Gridded Full Search



```
<?xml version="1.0" encoding="UTF-8"?>
<GriddedFullSearchConfig xmlns="http://www.opendata.org" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:schemaLocation="http://www
>   <costFunction weakParameterConstraint="false" class="org.opendata.algorithms.SimulationKwadraticCostFunction"/>
>   <!-- for each parameter a regular grid is defined. The computations cover all possible combinations of these values.
>   Note that the number of model runs increases quickly with the number of parameters, eg 10 steps for 3 parameters give 10x10x10=1000
>   <gridRange min="[7.0,1.5]" max="[9.0,1.8]" step="[0.2,0.05]"/>
>   <!-- optional additional criteria for stopping the calibration -->
>   <stopCriteria>
>     <stopCriterion class="org.opendata.algorithms.AbsoluteAveragePerLocationStopCriterion" threshold="1.0E-3"/>
>   </stopCriteria>
</GriddedFullSearchConfig>
```

- Test all combinations of parameters on a regular pattern
- Value with lowest cost is returned
- Parameters are in same order as in StochModel

# DUD Output



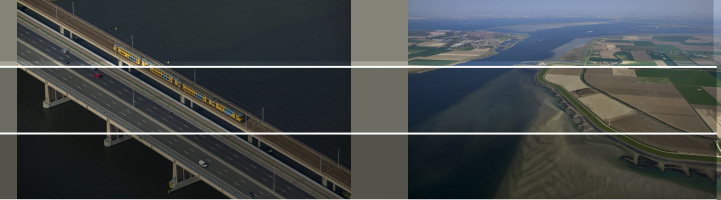
```
% =====
% DUD outer iteration no.1
% =====
% -----
costs{1}>      =[0.46925713409755426, 35.512591737499974, 37.30276589788343];
% -----
% Start search until improvement,
% Next try p=  [8.663,1.71]
% delta_p=    [0.663,0.014]
% =====
% prepare no 4
% configstring = OscillatorStochModel.xml
% opening : /home/verlaanm/deltares/src/openda_20101025/public/tests/simple_oscillator/./model/OscillatorStochModel.xml
% simulationTimespan =[0.0,0.05,10.0]
% parameters@names =t_damp,omega parameters=[8.0,1.5708]
% parameterUncertainty@names =t_damp,omega parameterUncertainty=[1.0,0.1257]
% systemNoise = {[0.0,0.0],[0.3,0.3]}
% initialState = [0.8,0.0]
% initialStateUncertainty = [0.8,0.8]
evaluatedParameters{4}> =[8.663227729470336,1.710474267579495];
% =====
% evaluate no. 4
predicted{4}>      =[-0.04871533545298321, -0.623329637530464, 0.18902524808841653, 0.4492358459183649, -0.25841736087328293, -0.29429346004168633, 0.
observed{4}>      =[-0.04313443918374465, -0.6309221702813459, 0.1759519292051853, 0.4657659569580843, -0.2452863996167396, -0.3179787785265744, 0.26
residuals{4}>      =[0.005580896269238564, -0.007592532750881897, -0.013073318883231239, 0.01653011103971941, 0.013130961256543339, -0.02368531848488
obs_stdev{4}>      =[0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1,0.1];
% -----
% -----
% RESIDUAL STATISTICS:
% -----
% ObsID>>      Num of data>>      Min>>      Max>>      Bias>>      STD>>      RMS
% -----
% 0.0>>      10>>      -0.02802444432221536>>      0.027600887633858262>>      -0.0016453322976147937>>      0.017827003466233938>>      0.016992026532941254
% -----
```

Estimated parameters from linear fit

Try full model with these pars

Results of full run

# DUD output



```
% Error estimate for this outer iteration
parameterErrorEstimateStd{3}>  =[1.574360951603447,0.020367356266850184];
parameterErrorCorrelations{3}> =[1.0,-0.11806660474049042,-0.11806660474049056,0.9999999999999998];
% stop criterion 1, imain > maxit:>      3 < 10
% stop criterion 2, diff < abstol:>      0.0017994068709786448 > 0.01
% stop criterion 3, relDiff < reltol:>    236.0017006534848 > 0.01
% stop criterion 4, linearized cost relative error: 0.004193543182922271 < 0.0010
% stop criterion AbsoluteAveragePerLocationStopCriterion: 1.0622549942029128E-5 > 1.0E-5
%>      >      satisfied at NO locations!
% =====
% SimulationKwadraticCostfunction: optimal results
%   number of evaluations: 6
%   all cost values:
%   [35.513,37.303,0.469,0.289,1.807E-3,7.625E-6]
%   all parameter values
%   [8,9,8,8.663,9.057,9.004;1.571,1.571,1.696,1.71,1.699,1.7]
%   number of observations: 10
%   best cost:
%   cost = 7.625E-6
%   best parameters:
%   [9.004,1.7]
% =====
% Application Done
```

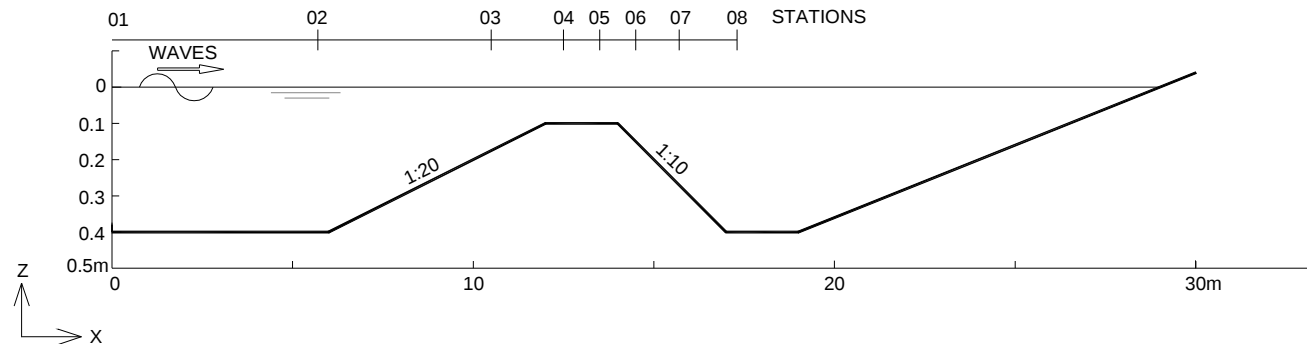
- Estimated errors (from accuracies in input and linear fit)
- Summary of calibration



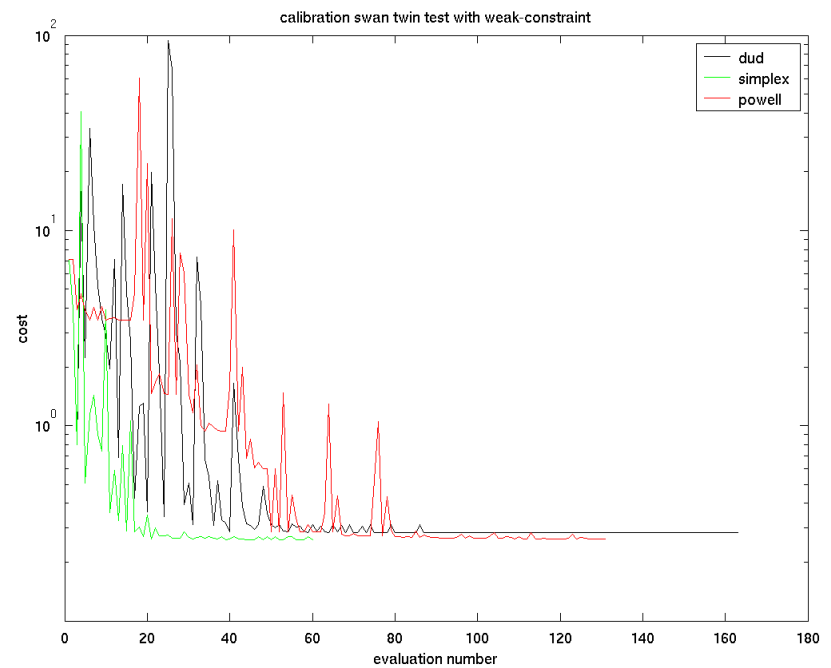
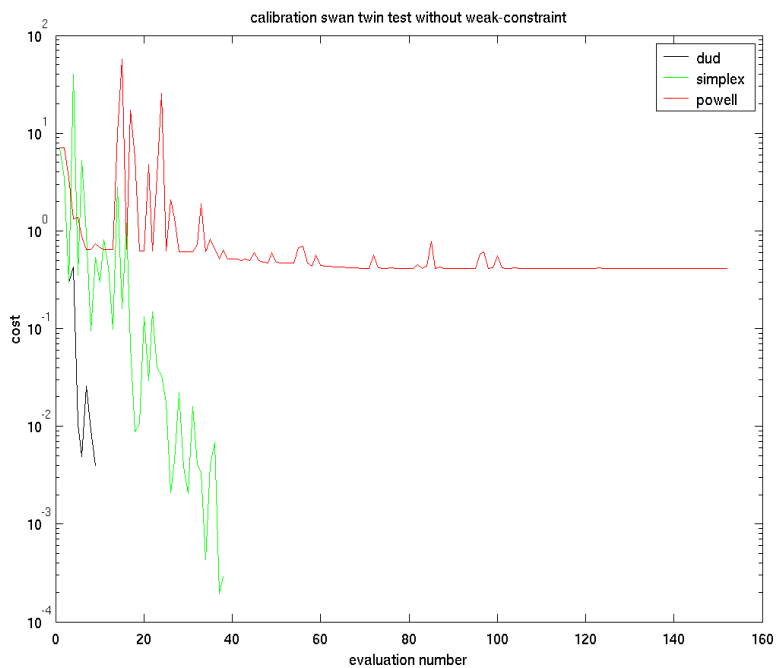
# SWAN: 3rd generation wave model

## Wave breaking and interaction over a bar

$S_{tot}$  = wind input + non-linear interactions (quadruplets &/+ triads) + whitecapping + bottom friction + depth induced wave breaking

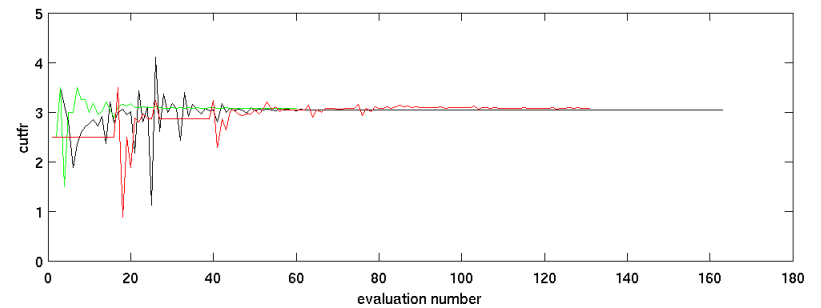
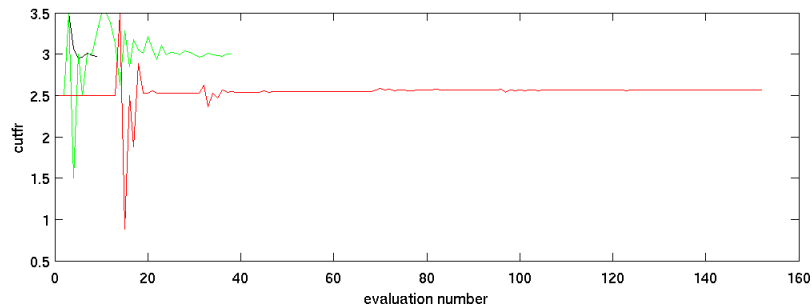
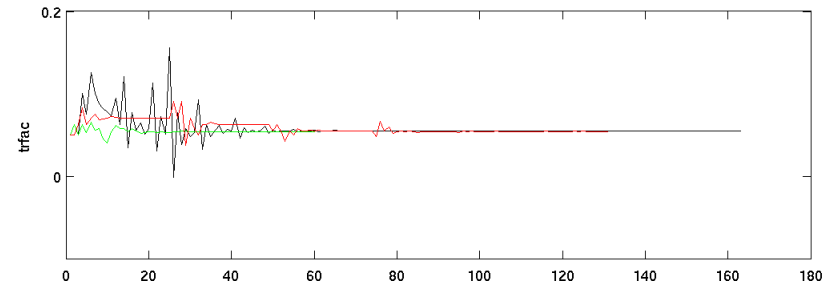
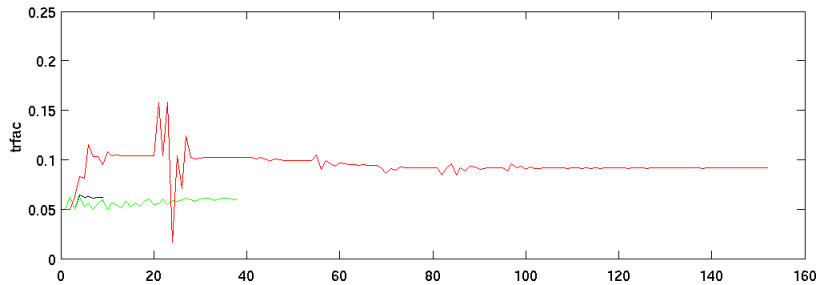


# SWAN calibration : costfunction



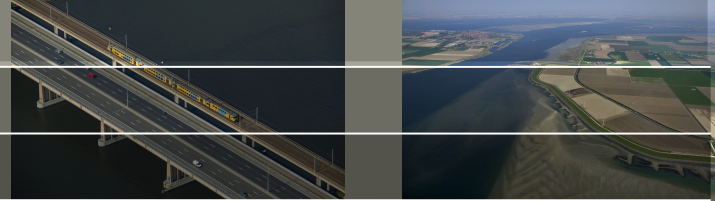
Local optimum: Powell does not converge here  
Weak constraint helps here: larger cost values

# SWAN calibration : parameter estimates



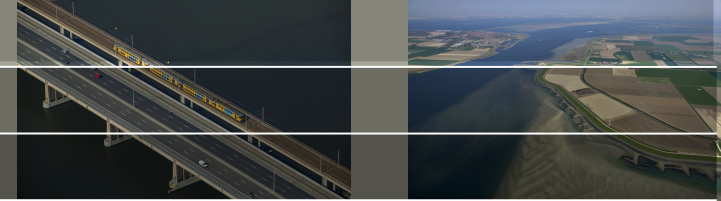
Weak constraint: closer to initial parameters

# Options



- Restarts
  - After a crash, when you need more iterations
- Parallel computing and scheduling
  - Modify blackbox wrapper
- Data selection
  - Observations are truncated in time based on simulation interval and options in StochObserver

# Restart



## Create restart files

```
<?xml version="1.0" encoding="UTF-8"?>
<openDaApplication>
<stochObserver className="org.openda.utils.CsvStochObserver">
<workingDirectory>./stochobserver</workingDirectory>
<configFile>observations_oscillator_generated_for_calibration.csv</configFile>
</stochObserver>
<b>restartOutFilePrefix>restart_</b></restartOutFilePrefix>
<stochModelFactory
className="org.openda.models.oscillator.OscillatorStochModelFactory">
...
```

## Use restart file

```
<b>restartInFile>restart_1.xml</b></restartInFile>
```

# Parallel computing/schedule runs

## Input file of Model wrapper:

```
<!-- computation actions -->
<!-- define actions relative to working dir. -->
<computeActions>
  <action workingDirectory="%instanceDir%" linuxExe="%OPENDADIR%/delftFlowRunQsub.sh" >
    <arg>%runid%</arg>
    <arg>%runid%_%instanceNumber%</arg>
  </action>
</computeActions>
<additionalComputeActions>
  <action workingDirectory="%instanceDir%" linuxExe="%OPENDADIR%/delftFlowRunWait.sh" >
    <arg>%runid%</arg>
    <arg>%runid%_%instanceNumber%</arg>
  </action>
</additionalComputeActions>
```

Use scripts to start and wait for runs.

# Time selection of observations

- Eg to exclude spin-up of model

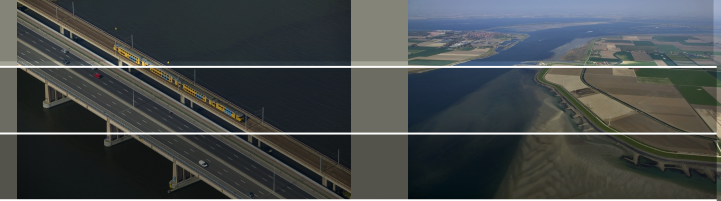
Blackbox model config file:

```
<timeInfo start="2009-01-01T00:00:00" end="2009-04-01T00:00:00"/>
```

Noos StochObserver:

```
<timeSeries status="validate" minDateTime="200901040000"  
MaxDateTime="200904010000" minValue="-3.0" maxValue="3.0" >  
  aberdeen_waterlevel_astro.noos  
</timeSeries>
```

# Final remarks



- Calibration tools only try to minimize the cost function. You have to provide the problem such that the results are meaningful.
- Look carefully at output files. Many things can go different than expected.